Eigenvalue Problems

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December 20, 2016

Theorem

For $B \in M_2(\mathbf{R})$, the following conditions are equivalent:

• (i) B is regular.

• (ii)
$$B\vec{v} = \vec{0} \Rightarrow \vec{v} = \vec{0}$$

Theorem

For $B \in M_2(\mathbf{R})$, the following conditions are equivalent:

- **NOT(i)** *B* is not regular (singular).
- **NOT(ii)** There exists $\vec{v} \neq \vec{0}$ satisfying $B\vec{v} = \vec{0}$.
- **NOT(iii)** |B| = 0

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Example (1)

Let
$$A = \begin{pmatrix} 1 & 2 \\ 4 & 3 \end{pmatrix}$$
. We consider the system of equations:
$$A \begin{pmatrix} x \\ y \end{pmatrix} = \lambda \begin{pmatrix} x \\ y \end{pmatrix}$$

First remark that the system is equivalent to

(#)
$$(\lambda I_2 - A) \begin{pmatrix} x \\ y \end{pmatrix} = \vec{0}$$
, where $\lambda I_2 - A = \begin{pmatrix} \lambda - 1 & -2 \\ -4 & \lambda - 3 \end{pmatrix}$

We also remark that

$$|\lambda I_2 - A| = \begin{vmatrix} \lambda - 1 & -2 \\ -4 & \lambda - 3 \end{vmatrix} = (\lambda + 1)(\lambda - 5)$$

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$$\frac{\ln \text{ case } \lambda \neq -1,5}{\ln \text{ case } \lambda = -1} (\#) \Leftrightarrow \begin{pmatrix} x \\ y \end{pmatrix} = \vec{0}$$

$$(\#) \Leftrightarrow \begin{pmatrix} -2 & -2 \\ -4 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \vec{0} \Leftrightarrow x + y = 0$$

We put y = t to get the solution

$$\binom{x}{y} = \binom{-t}{t} = t \binom{-1}{1}$$

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In case $\lambda = 5$

$$(\#) \Leftrightarrow \begin{pmatrix} 4 & -2 \\ -4 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \vec{0} \Leftrightarrow 2x - y = 0$$

We put y = t to get the solution

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} t \\ 2t \end{pmatrix} = t \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

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Diagonalization (1)

We define two vectors

$$ec{p}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad ec{p}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

and a 2×2 matrix

$$P=(ec{p}_1 \,\, ec{p}_2)=egin{pmatrix} -1 & 1 \ 1 & 2 \end{pmatrix}$$

The matrix P is regular since

$$|P| = \begin{vmatrix} -1 & 1 \\ 1 & 2 \end{vmatrix} = -3 \neq 0$$

Diagonalization (2)

$$\begin{aligned} AP &= A(\vec{p}_1 \ \vec{p}_2) = (A\vec{p}_1 \ A\vec{p}_2) \\ &= (-\vec{p}_1 \ 5\vec{p}_2) \\ &= (\vec{p}_1 \ \vec{p}_2) \begin{pmatrix} -1 & 0 \\ 0 & 5 \end{pmatrix} = P \begin{pmatrix} -1 & 0 \\ 0 & 5 \end{pmatrix} \end{aligned}$$

We multiply P^{-1} from the left to get

$$P^{-1}AP = \begin{pmatrix} -1 & 0 \\ 0 & 5 \end{pmatrix}$$

This process is called a diagonalization of A. To see how it dows mean, we introduce the coordinate transform given by

$$\begin{pmatrix} x \\ y \end{pmatrix} = \xi \vec{p}_1 + \eta \vec{p}_2 = (\vec{p}_1 \ \vec{p}_2) \begin{pmatrix} \xi \\ \eta \end{pmatrix} = P \begin{pmatrix} \xi \\ \eta \end{pmatrix}$$

Diagonalization (3)

In this situation the map

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix}$$

can be clarified by using the coordinate transform as follows.

$$\begin{pmatrix} \xi' \\ \eta' \end{pmatrix} = P^{-1} \begin{pmatrix} x' \\ y' \end{pmatrix}$$

$$= P^{-1} A \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= P^{-1} A P \begin{pmatrix} \xi \\ \eta \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & 5 \end{pmatrix} \begin{pmatrix} \xi \\ \eta \end{pmatrix}$$