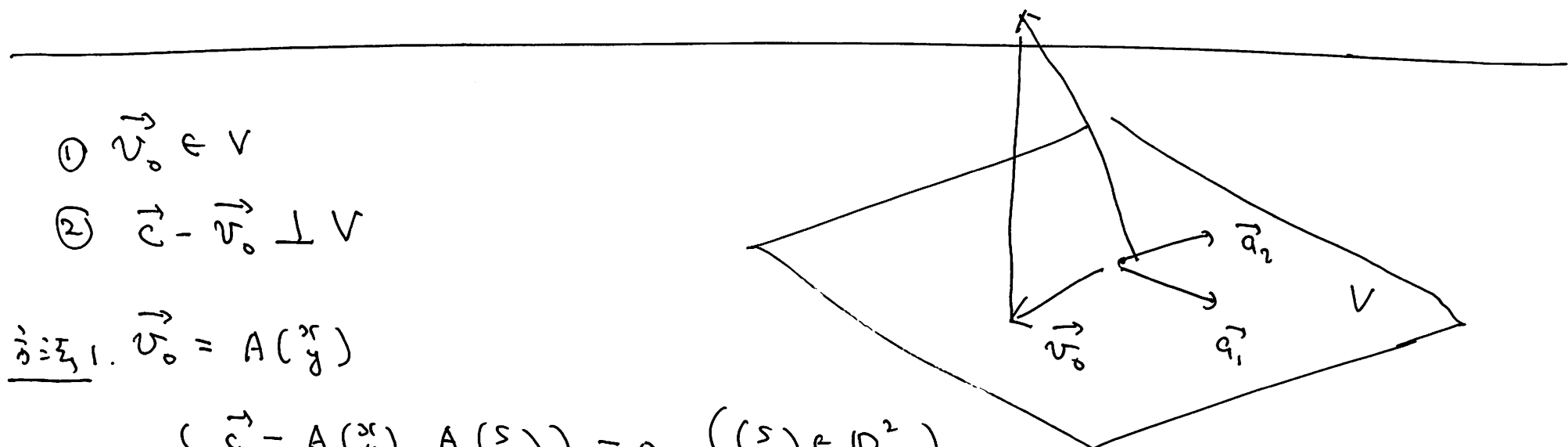


$$\vec{a}_1 = \begin{pmatrix} - \\ - \\ 1 \end{pmatrix}, \vec{a}_2 = \begin{pmatrix} - \\ 0 \\ -2 \end{pmatrix}, \vec{c} = \begin{pmatrix} - \\ 0 \\ 0 \end{pmatrix} \quad A = (\vec{a}_1 \vec{a}_2)$$

$$\underset{V}{\overset{\mathbb{C}}{\mathbb{C}}} \cap \text{Im}(A) = \left\{ x \vec{a}_1 + y \vec{a}_2 ; x, y \in \mathbb{R} \right\} \cap \mathbb{C} \text{ 的交集}$$



① $\vec{c}_0 \in V$

② $\vec{c} - \vec{c}_0 \perp V$

欲求 $\vec{c}_0 = A \begin{pmatrix} x \\ y \end{pmatrix}$

$$(\vec{c} - A \begin{pmatrix} x \\ y \end{pmatrix}, A \begin{pmatrix} x \\ y \end{pmatrix}) = 0 \quad \left(\begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 \right)$$

\Leftrightarrow

$${}^t A A \begin{pmatrix} x \\ y \end{pmatrix} = {}^t A \vec{c} \quad \dots$$

$V = I_m(A)$ の正規直交基底を求めよ。

$$\|\vec{a}_1\| = 2, \|\vec{a}_2\| = \sqrt{6}, (\vec{a}_1, \vec{a}_2) = 2$$

\vec{a}_2 の \vec{a}_1 方向の直交射影を \vec{w}

$$\vec{w} = \frac{(\vec{a}_1, \vec{a}_2) \vec{a}_1}{\|\vec{a}_1\|^2} = \frac{2}{4} \vec{a}_1 = \frac{1}{2} \vec{a}_1$$

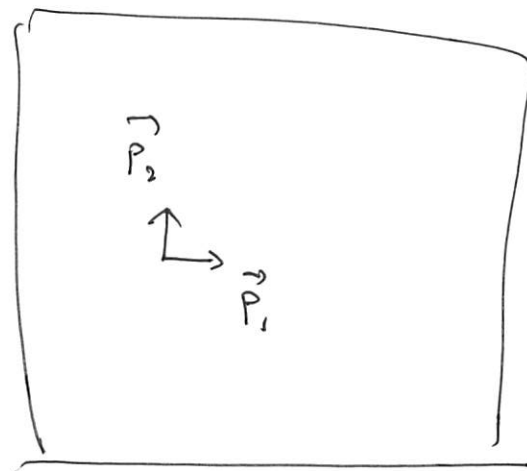
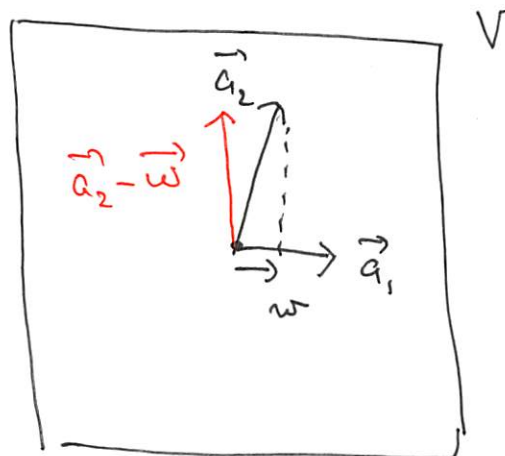
$$\vec{a}_2 - \vec{w} \perp \vec{a}_1$$

$$\vec{a}_2 - \vec{w} = \begin{pmatrix} 1 \\ 0 \\ 2 \\ -1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{3}{2} \\ \frac{1}{2} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 3 \\ 1 \end{pmatrix}$$

$$\vec{p}_1 = \frac{1}{\|\vec{a}_1\|} \vec{a}_1 = \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix}, \vec{p}_2 = \frac{1}{\|\vec{a}_2 - \vec{w}\|} (\vec{a}_2 - \vec{w})$$

$$\rightarrow \|\vec{p}_1\| = \|\vec{p}_2\| = 1, (\vec{p}_1, \vec{p}_2) = 0$$

V の正規直交基底



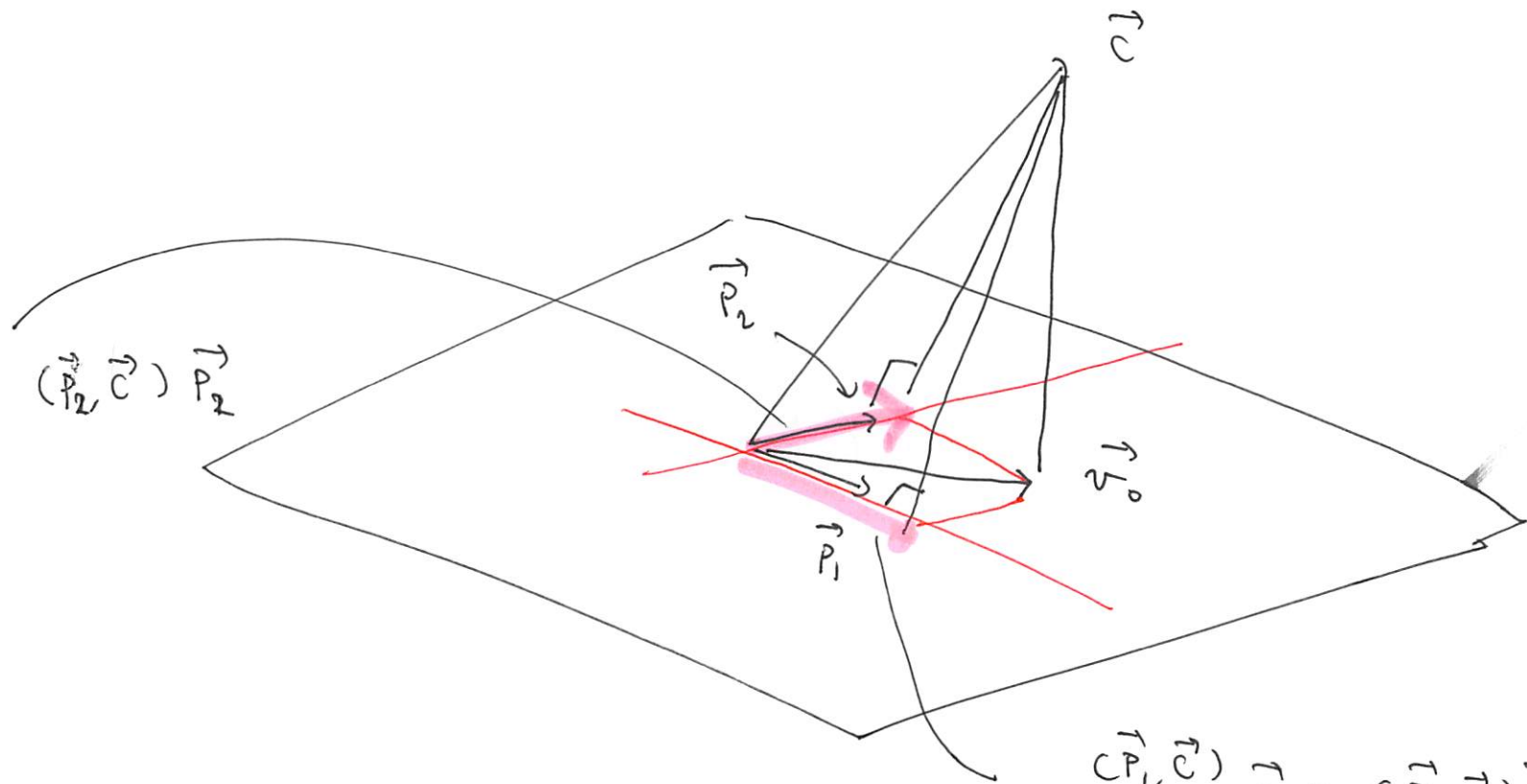
$$\vec{c} = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \text{ 是 } V \text{ 的 正交射影}$$

$$\vec{s} = (\vec{p}_1, \vec{c}) \vec{p}_1 + (\vec{p}_2, \vec{c}) \vec{p}_2$$

$$= \left(\frac{1}{2} \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \right) \cdot \frac{1}{2} \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} + \left(\frac{1}{\sqrt{20}} \begin{pmatrix} -1 \\ 3 \\ 3 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix} \right) \cdot \frac{1}{\sqrt{20}} \begin{pmatrix} -1 \\ 3 \\ 3 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix} + \frac{1}{20} \begin{pmatrix} -1 \\ 3 \\ 3 \end{pmatrix} = \frac{1}{20} \begin{pmatrix} 5+1 \\ 5-1 \\ 5+3 \\ -5+3 \end{pmatrix} = \frac{1}{20} \begin{pmatrix} 6 \\ 4 \\ 8 \\ -2 \end{pmatrix}$$

$$= \frac{1}{5} \begin{pmatrix} 3 \\ 2 \\ 4 \\ -1 \end{pmatrix}$$



$$\frac{(P_1, c)}{\|P_1\|^2} P_1 = (P_1, c) P_1$$

↑
 $\|P_1\| = 1$

$$W = \{ x \vec{a}_1 + y \vec{a}_2 + z \vec{c}; x, y, z \in \mathbb{R} \}$$

W 的 基 是 $\vec{P}_1, \vec{P}_2, \vec{P}_3$

$$\|\vec{P}_i\|^2 = 1$$

W 的 正 交 基 是

$$(\vec{P}_i, \vec{P}_j) = 0 \quad (i \neq j)$$

$$\vec{v}_0 \perp V$$

$$\vec{v}_0 = * \vec{p}_1 + * \vec{p}_2 \in V$$

$$\vec{v}_0 = \begin{pmatrix} 2 \\ 1 \\ 0 \\ 0 \end{pmatrix} - \begin{pmatrix} 3 \\ 2 \\ 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\|\vec{p}_1\| = \|\vec{p}_2\| = \|\vec{p}_3\| = 1$$

$$\langle \vec{p}_1, \vec{p}_2 \rangle = 0$$

$$\langle \vec{p}_1, \vec{p}_3 \rangle = \langle \vec{p}_2, \vec{p}_3 \rangle = 0$$

$$\vec{v}_0 = * \vec{p}_1 + * \vec{p}_2 \in V$$

$$\vec{v}_0 = \frac{1}{\sqrt{2}} (\vec{p}_2 - * \vec{p}_1)$$

$$\vec{v}_0 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 2 \\ 1 \\ -1 \end{pmatrix}$$

$$\vec{v}_0 \perp V \quad \leftarrow \quad \vec{v}_3 \perp V$$

$$\begin{pmatrix} 1 \\ 2 \\ 1 \\ -1 \end{pmatrix}$$

$$\vec{v}_0 \perp V$$

Lagrange 不定乗法

3変数. 1制約条件.

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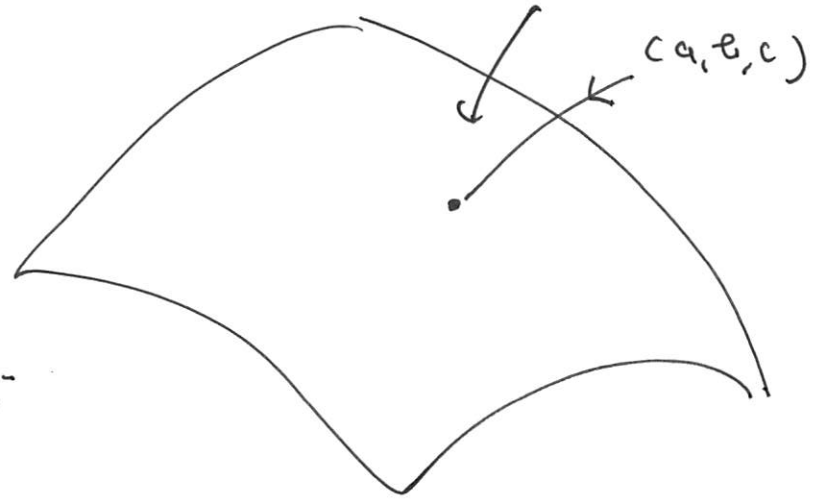
$f(x, y, z) = 0$ a 下 z $w = f(x, y, z)$

$f(x, y, z) = 0$

陰関数定理



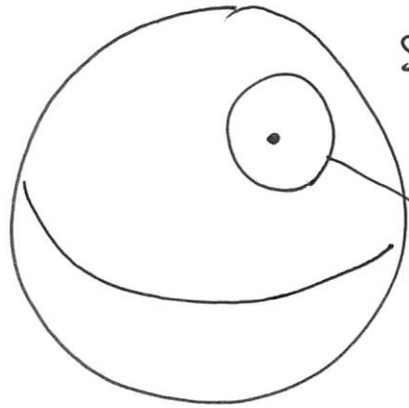
$f_z(a, b, c) \neq 0$
 $f(a, b, c) = 0$



$\Rightarrow (a, b, c) \in \mathbb{R}^3$

(曲) $f(x, y, z) = 0$ 上

$z = f(x, y)$ と書ける.



$S: f(x, y, z) = x^2 + y^2 + z^2 - 1 = 0$

$(a, b, c) \in S$

$f_z = 2z \neq 0$

$\leadsto c \neq 0$

$z = \pm 1$

$f(x, y) = \sqrt{1 - x^2 - y^2}$

$$F(x, y) = f(x, y, g(x, y))$$

$$(a, b, c) \in F^{-1}(z) \implies F_x(a, b) = F_y(a, b) = 0$$

Chain Rule \longrightarrow $\frac{d}{dt} f(x(t), y(t), z(t)) = P_t$

$$= f_x(P_t) x'(t) + f_y(P_t) y'(t) + f_z(P_t) z'(t).$$

$$F(s, t) = f(s, t, g(s, t))$$

$$F_s = f_x(\cdot) \cdot 1 + f_y(\cdot) \cdot 0 + f_z(\cdot) \cdot g_s(s, t).$$

$t \in F^{-1}(z) \implies F_t = f_x(\cdot) \cdot 0 + f_y(\cdot) \cdot 1 + f_z(\cdot) \cdot g_t(s, t)$

$$\left\{ \begin{aligned} F_s(a, b) &= f_x(a, b, c) + f_z(a, b, c) \cdot \underline{g_s(a, b)} = 0 \end{aligned} \right.$$

$$\left\{ \begin{aligned} F_t(a, b) &= f_y(a, b, c) + f_z(a, b, c) \cdot \underline{g_t(a, b)} = 0 \end{aligned} \right.$$

$$g(s, t, g(s, t)) \equiv 0 \quad ((a, e, c) \text{ 附近 } \subset \mathbb{R}^3)$$

set \mathbb{R}^3 附近

$$\begin{cases} g_x(\cdot) \cdot 1 + g_y(\cdot) \cdot 0 + g_z(\cdot) \cdot g_s(s, t) \equiv 0 \\ g_x(\cdot) \cdot 0 + g_y(\cdot) \cdot 1 + g_z(\cdot) \cdot g_t(s, t) \equiv 0 \end{cases}$$

$$s = a, t = e \in \mathbb{R}^2. \quad P_0(a, e, c)$$

$$\begin{cases} g_x(P_0) + g_z(P_0) g_s(a, e) = 0 \\ g_y(P_0) + g_z(P_0) g_t(a, e) = 0 \end{cases}$$

$$\rightarrow g_s(a, e) = -\frac{g_x(P_0)}{g_z(P_0)}, \quad g_t(a, e) = -\frac{g_y(P_0)}{g_z(P_0)}$$

\mathbb{R}^3

$$\begin{cases} f_x(P_0) + \left(-\frac{f_z(P_0)}{g_z(P_0)}\right) g_x(P_0) = 0 \\ f_y(P_0) + \left(-\frac{f_z(P_0)}{g_z(P_0)}\right) g_y(P_0) = 0 \end{cases}$$

$$\lambda = -\frac{f_z(P_0)}{g_z(P_0)} \quad \varepsilon \mathbb{R}^1 \subset \mathbb{R}$$

$$\textcircled{\#} \begin{cases} f_x(P_0) + \lambda g_x(P_0) = 0 \\ f_y(P_0) + \lambda g_y(P_0) = 0 \\ f_z(P_0) + \lambda g_z(P_0) = 0 \end{cases} \iff \begin{aligned} \nabla(f)(P_0) + \lambda \nabla(g)(P_0) \\ = 0 \end{aligned}$$

接点条件.

定理

$g(x, y, z) = 0$ の下で $w = f(x, y, z)$ を考える

$$\begin{cases} g_z(a, b, c) \neq 0 \\ g(a, b, c) = 0 \end{cases} \text{ が成り立つ.}$$

(a, b, c) が g の極値点ならば $\textcircled{\#}$ を満たす λ が存在.

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$$g(x, y, z) = x^2 + y^2 + z^2 - 1 = 0. \quad \dots \textcircled{0}$$

а 7 2

$$w = f(x, y, z) = 3x - y + 2z.$$

$$\begin{cases} 3 + \lambda \cdot 2x = 0 \\ -1 + \lambda \cdot 2y = 0 \\ 2 + \lambda \cdot 2z = 0 \end{cases}$$

$$\text{Или} \quad \begin{cases} x = -\frac{3}{2\lambda} \\ y = \frac{1}{2\lambda} \\ z = -\frac{1}{\lambda} \end{cases}$$

$\textcircled{0} \quad 1 = 5\lambda^2$

$$1 = \frac{9}{4\lambda^2} + \frac{1}{4\lambda^2} + \frac{4}{\lambda^2}$$

$$\lambda^2 = \frac{14}{4}$$

$$\lambda = \pm \frac{\sqrt{14}}{2}$$

$$x = \mp \frac{3}{\sqrt{14}}, \quad y = \pm \frac{1}{\sqrt{14}}, \quad z = \mp \frac{2}{\sqrt{14}}$$

$$\frac{1}{\lambda} = \pm \frac{2}{\sqrt{14}}$$

$$g(x, y, z) = \lambda_1 z \quad \nabla(g) = \begin{pmatrix} 0 \\ 0 \\ \lambda_1 \end{pmatrix}$$

$$\nabla(g)(P_0) = \lambda_1 \mathbf{e}_3$$

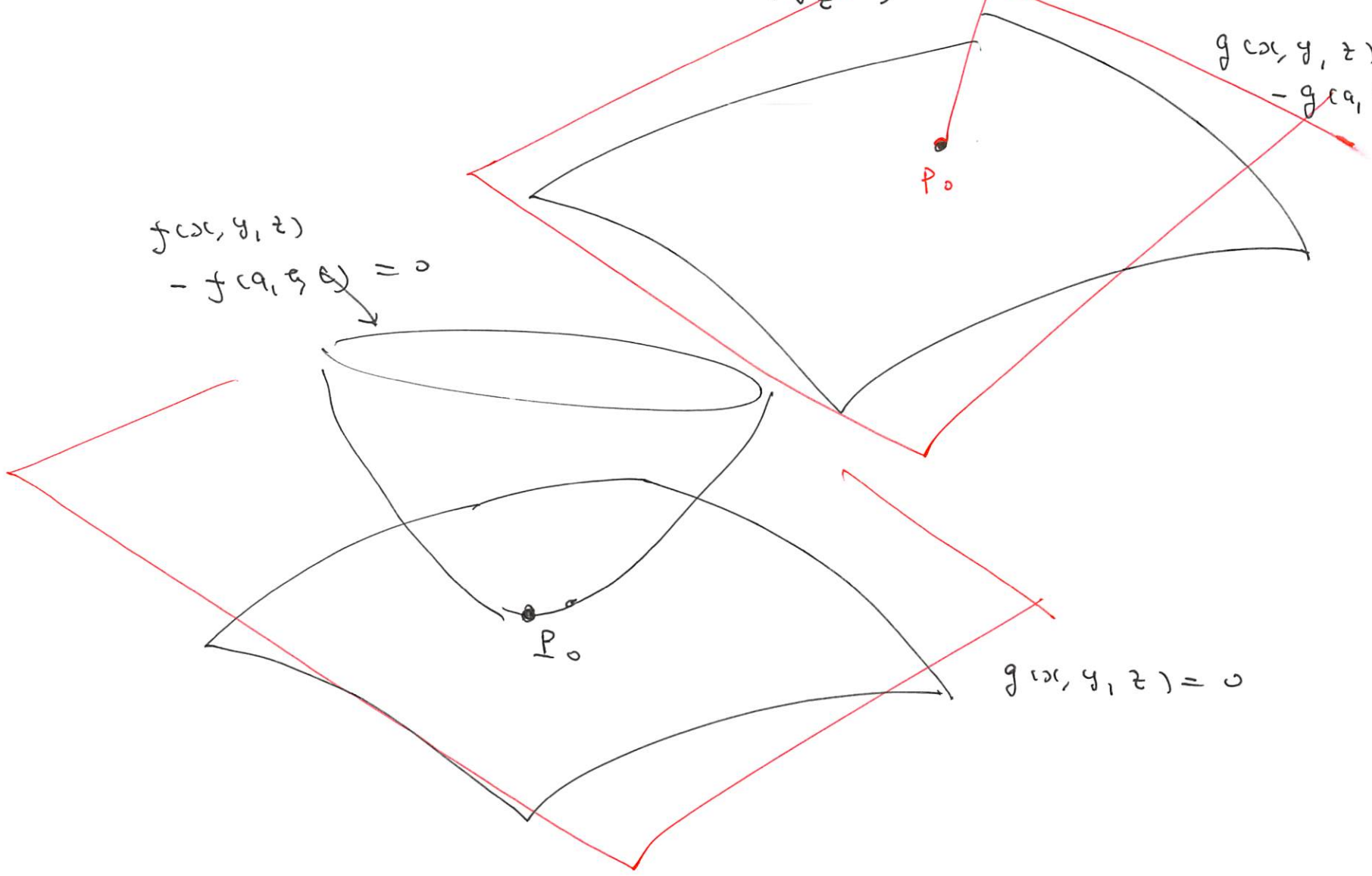
$$g(x, y, z) - g(a, b, c) = 0$$

$$f(x, y, z) - f(a, b, c) = 0$$

$$g(x, y, z) = 0$$

P_0

P_0



$$g(x, y, z) = x + y + z - 1 = 0 \quad \text{の下 } z^{-1}$$

$$w = f(x, y, z) = x^2 + 4y^2 + 9z^2 \quad \text{を考へる.}$$

停留点を求めよ. 未定乗数も求めよ.
