

10/14

$z = x^2 - xy + y^2$ の $(1, 1, 1)$ に接する接平面.

$z = f(x, y)$ の $(a, b, f(a, b))$ に接する接平面.

$$z = f_x(a, b)(x-a) + f_y(a, b)(y-b) + f(a, b)$$

$$z_x = 2x - y \cdot 1 + 0$$

$$= 2x - y.$$

$$\rightsquigarrow z_x(1, 1) = 1$$

$$z_y = 0 - x \cdot 1 + 2y$$

$$= -x + 2y$$

$$z_y(1, 1) = 1$$

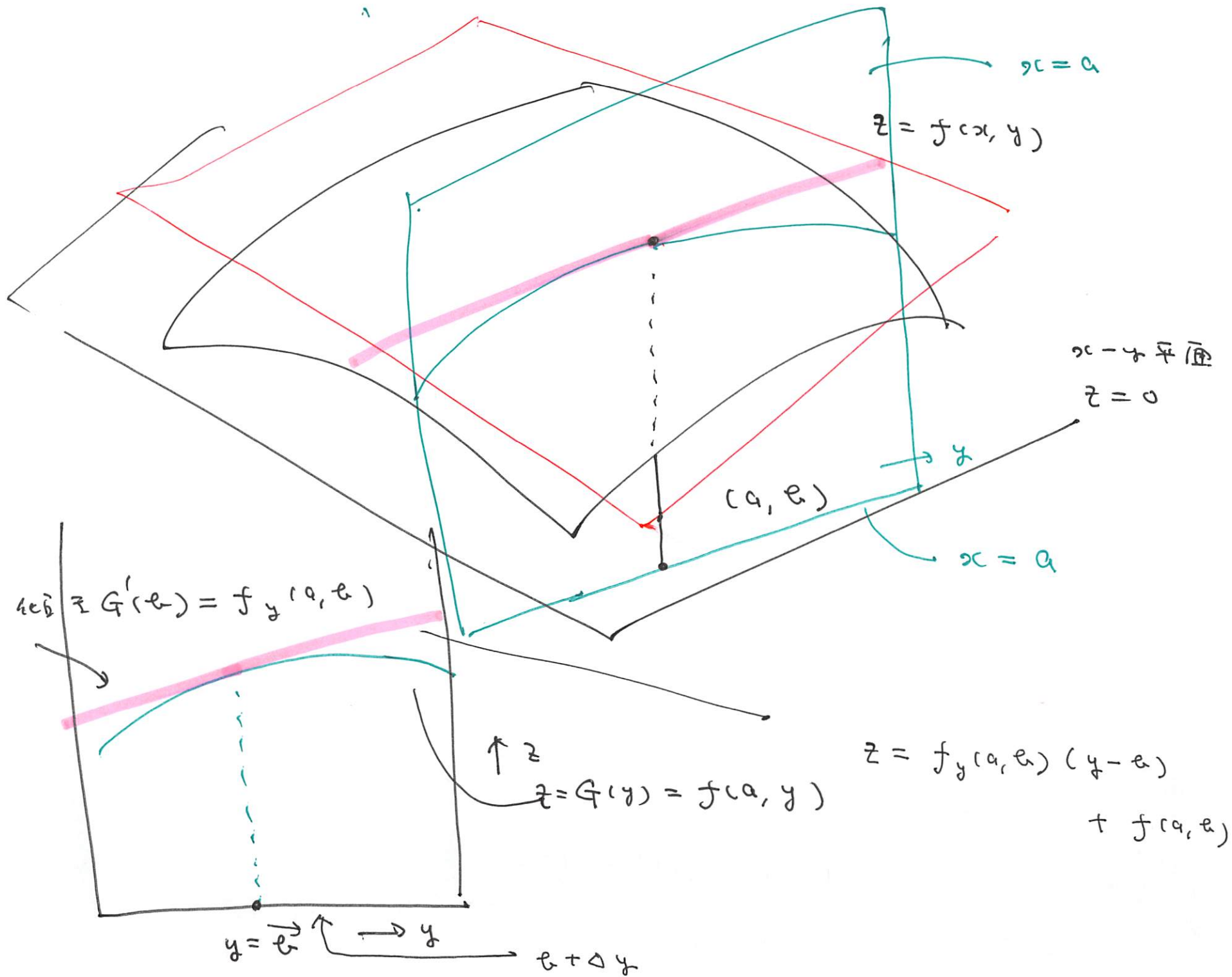
∴ 接平面は

$$z = 1 \cdot (x-1) + 1 \cdot (y-1) + 1$$

可なり

$$z = (x-1) + (y-1) + 1$$

$$\rightsquigarrow z = x + y - 1$$



$$z = A(x - a) + B(y - b) + f(a, b)$$

फंक्शन

$$\xrightarrow{x = a} z = B(y - b) + f(a, b)$$

$$B = f'(b) = f_y(a, b)$$

$$f(a, b + \Delta y) \approx f_y(a, b) \Delta y + f(a, b)$$

§7.3.1 行列の定義

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left(\begin{array}{c} \vec{a}_1 \\ \vec{a}_2 \end{array} \right) = \begin{pmatrix} a_{11} \\ a_{12} \end{pmatrix}$$

3行×5列 5行×5列

$$\begin{aligned} A \begin{pmatrix} x \\ y \end{pmatrix} &= x \vec{a}_1 + y \vec{a}_2 = x \begin{pmatrix} a \\ c \end{pmatrix} + y \begin{pmatrix} b \\ d \end{pmatrix} \\ &= \begin{pmatrix} xa + yb \\ xc + yd \end{pmatrix} = \begin{pmatrix} (a \ b) \begin{pmatrix} x \\ y \end{pmatrix} \\ (c \ d) \begin{pmatrix} x \\ y \end{pmatrix} \end{pmatrix} = \begin{pmatrix} a_{11} \begin{pmatrix} x \\ y \end{pmatrix} \\ a_{12} \begin{pmatrix} x \\ y \end{pmatrix} \end{pmatrix} \end{aligned}$$

$$\underbrace{(\alpha_1 \ \alpha_2 \ \dots \ \alpha_n)}_{\vec{\alpha}} \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{pmatrix} = \alpha_1 \beta_1 + \alpha_2 \beta_2 + \dots + \alpha_n \beta_n$$

$$= \left(\begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{pmatrix}, \begin{pmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{pmatrix} \right)$$

$$(\vec{\alpha}, \vec{\beta}) = \vec{\alpha} \vec{\beta}$$

$\exists t \in \mathcal{A}$ $A = (\vec{a}_1 \ \vec{a}_2) = \begin{pmatrix} a_{11} \\ a_{12} \end{pmatrix} \ 2 \times 2, \ \vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}$

$$A \vec{v} = x \vec{a}_1 + y \vec{a}_2 = \begin{pmatrix} a_{11} \vec{v} \\ a_{12} \vec{v} \end{pmatrix} \in \mathbb{R}^2$$

例 1

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = (a_1 \ a_2) = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$$

$${}^t A = \begin{pmatrix} a & c \\ b & d \end{pmatrix} = ({}^t a_1 \ {}^t a_2) = \begin{pmatrix} {}^t a_1 \\ {}^t a_2 \end{pmatrix} \quad \text{transposition of } A$$

例 2

$$\vec{v} \in \mathbb{R}^2 \quad (A \vec{v} \in \mathbb{R}^2), \quad \vec{w} \in \mathbb{R}^2$$
$$(A \vec{v}, \vec{w}) = (\vec{v}, {}^t A \vec{w})$$

$$\vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}$$

(証明) $(T_2) = (x a_1 + y a_2, \vec{w})$

$$= x (a_1, \vec{w}) + y (a_2, \vec{w})$$

$${}^t a_1 = (a \ c)$$

$${}^t a_2 = (b \ d)$$

$$= x {}^t a_1 \vec{w} + y {}^t a_2 \vec{w}$$

$$= \left(\begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} {}^t a_1 \vec{w} \\ {}^t a_2 \vec{w} \end{pmatrix} \right)$$

$$= \begin{pmatrix} {}^t a_1 \\ {}^t a_2 \end{pmatrix} \vec{w} = {}^t A \vec{w}$$

$$= (\vec{v}, {}^t A \vec{w}) = (T_2)$$

$$A = \begin{pmatrix} a & c \\ c & e \end{pmatrix} \quad \text{且 } \det A \neq 0 \quad \vec{\beta} = \begin{pmatrix} d \\ e \end{pmatrix}$$

$$f(x, y) = ax^2 + 2cxy + ey^2 + dx + ey + f$$

$$= \left(A \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + \left(\vec{\beta}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + f$$

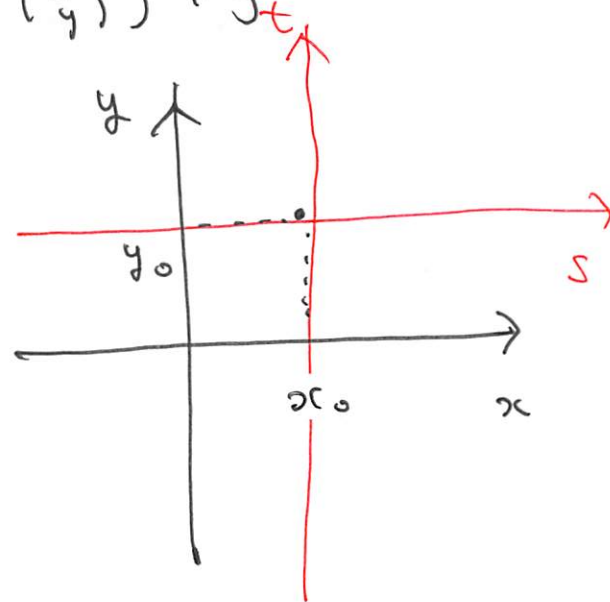
$A \text{ 为 } 2 \times 2 \text{ 实对称阵}$

配方

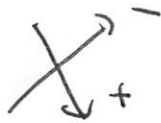
$$\begin{pmatrix} s \\ t \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$

$$\vec{w} = \vec{v} - \vec{v}_0$$

$$\vec{w} = \begin{pmatrix} s \\ t \end{pmatrix}, \quad \vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}, \quad \vec{v}_0 = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$$



且 $|A| = ae - c^2 \neq 0 \in \mathbb{R}$



$$f(x, y) = (A\vec{u}, \vec{u}) + (\vec{\beta}, \vec{u}) + f.$$

$$= (A(\vec{w} + \vec{u}_0), \vec{w} + \vec{u}_0) + (\vec{\beta}, \vec{w} + \vec{u}_0) + f$$

$$\vec{u} = \vec{w} + \vec{u}_0$$

Σ代換

各因. tA の x, y

$$= (A\vec{w}, \vec{w}) + 2(A\vec{u}_0, \vec{w}) + (\vec{\beta}, \vec{w}) + (A\vec{u}_0, \vec{u}_0) + (\vec{\beta}, \vec{u}_0) + f.$$

$$= (2A\vec{u}_0 + \vec{\beta}, \vec{w}) = *_1 s + *_2 t.$$

$$\begin{pmatrix} * \\ * \end{pmatrix} \quad \begin{pmatrix} s \\ t \end{pmatrix}$$

||
定数

s, t = 任意

$$= as^2 + 2st + ct^2$$

$$\vec{u}_0 = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \quad \Sigma \quad 2A\vec{u}_0 + \vec{\beta} = \vec{0} \quad \text{と可解} \quad \text{定数}$$

$$\vec{u}_0 = -\frac{1}{2} A^{-1} \vec{\beta} \quad \text{と可解}$$

3.10 $\vec{z}_0 = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix}$ $\vec{v}_0 = -\frac{1}{2} A^{-1} \vec{\beta}$ $\epsilon \ll \epsilon^2$

$$f(x, y) = \left(A \begin{pmatrix} s \\ t \end{pmatrix}, \begin{pmatrix} s \\ t \end{pmatrix} \right) + f'$$

$$= as^2 + 2cst + at^2$$

$$\text{1D} \quad \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} s \\ t \end{pmatrix} + \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \quad \Downarrow \quad \vec{z} = \vec{z}_0 + \vec{v}_0$$

$$f' = \underbrace{\left(A \vec{v}_0, \vec{v}_0 \right) + \left(\vec{\beta}, \vec{v}_0 \right) + f}_{= f(x=x_0, y=y_0)}$$

$$f(x, y) = \left(A \vec{v}, \vec{v} \right) + \left(\vec{\beta}, \vec{v} \right) + f.$$

別の点 $\frac{df}{dt} = \Sigma$.

$$z = x^2 - xy + y^2 - 2x + 4y$$

$$= s^2 - st + t^2 + f'$$

$$\Rightarrow (x-a)^2 - (x-a)(y-b) + (y-b)^2 + f'$$

常に成立

x について微分

$$2x - y - 2 = 2(x-a) - (y-b)$$

y について微分

$$-x + 2y + 4 = -(x-a) + 2(y-b)$$

$$\begin{cases} 2a - b - 2 = 0 \\ -a + 2b + 4 = 0 \end{cases}$$

$$\rightsquigarrow (a, b) = (0, -2)$$

$x = a = 0$
 $y = b = -2$

$$\begin{aligned} ((t-a)^n)' &= n(t-a)^{n-1} \cdot 1 \end{aligned}$$

↓

$$\begin{aligned} 4 + 4(-2) &= f' \\ -4 & \end{aligned}$$

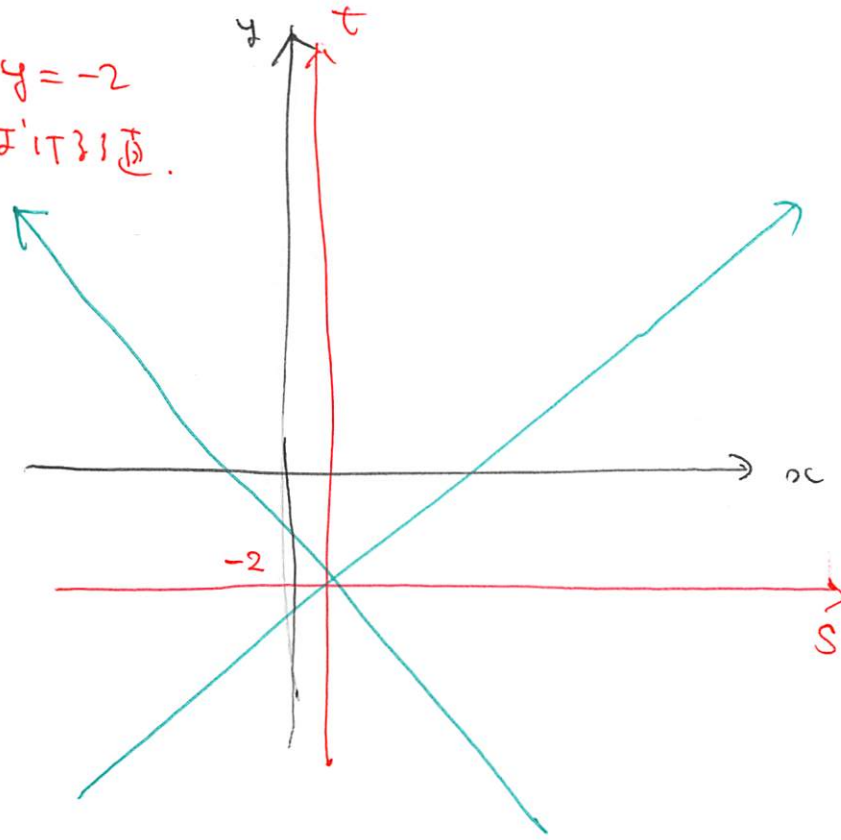
$$z \text{ の } x=0, y=-2$$

$= \pi$ の直線.

$$z = s^2 - st + t^2 - 4$$

回転座標変換.

\downarrow
 $= \pi$ の直線.



法線ベクトル

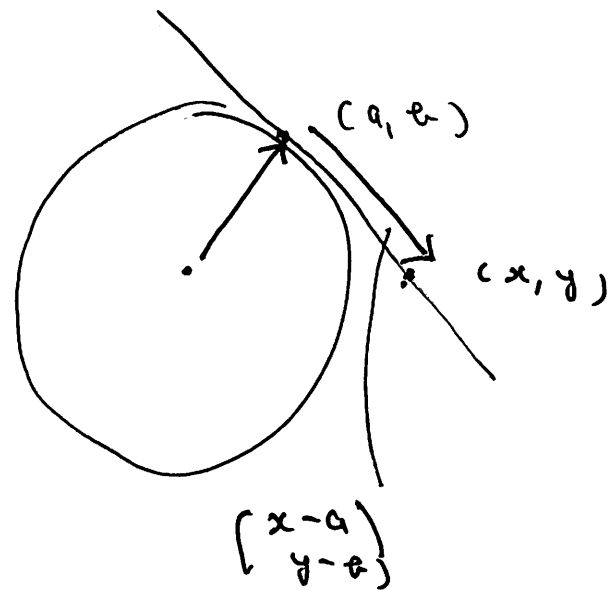
$$g(x, y) = x^2 + y^2 - 1 = 0$$

$a(a, e)$ は法線ベクトル

$$ax + ey = 1$$

$$\begin{pmatrix} a \\ e \end{pmatrix} \cdot \begin{pmatrix} x-a \\ y-e \end{pmatrix} = 0$$

$$\begin{aligned} \rightarrow a(x-a) + e(y-e) = 0 &\rightarrow ax + ey = 1 \\ &\uparrow \\ &a^2 + e^2 = 1 \end{aligned}$$



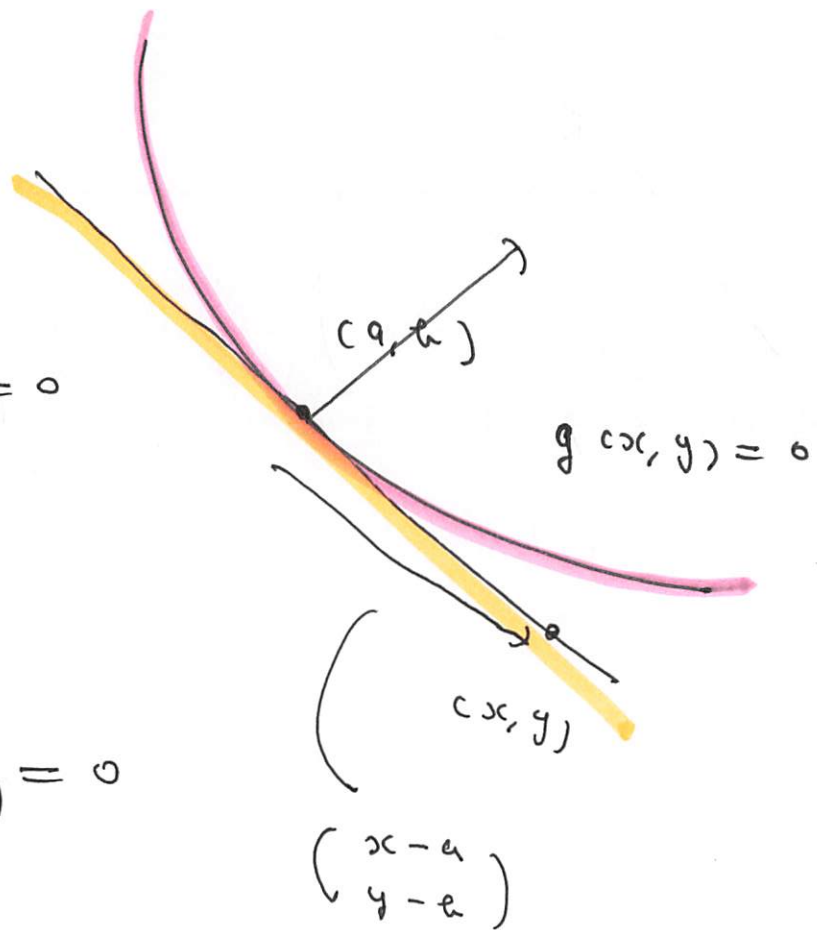
梯度法

$$g_x(a, b)(x-a) + g_y(a, b)(y-b) = 0$$

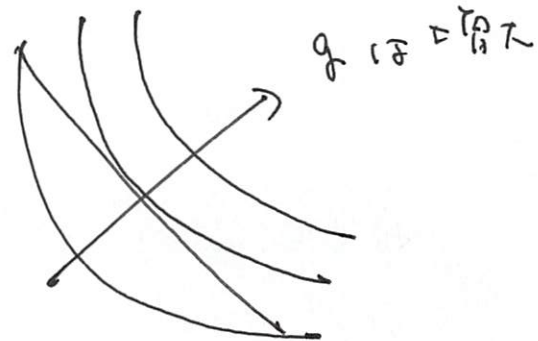


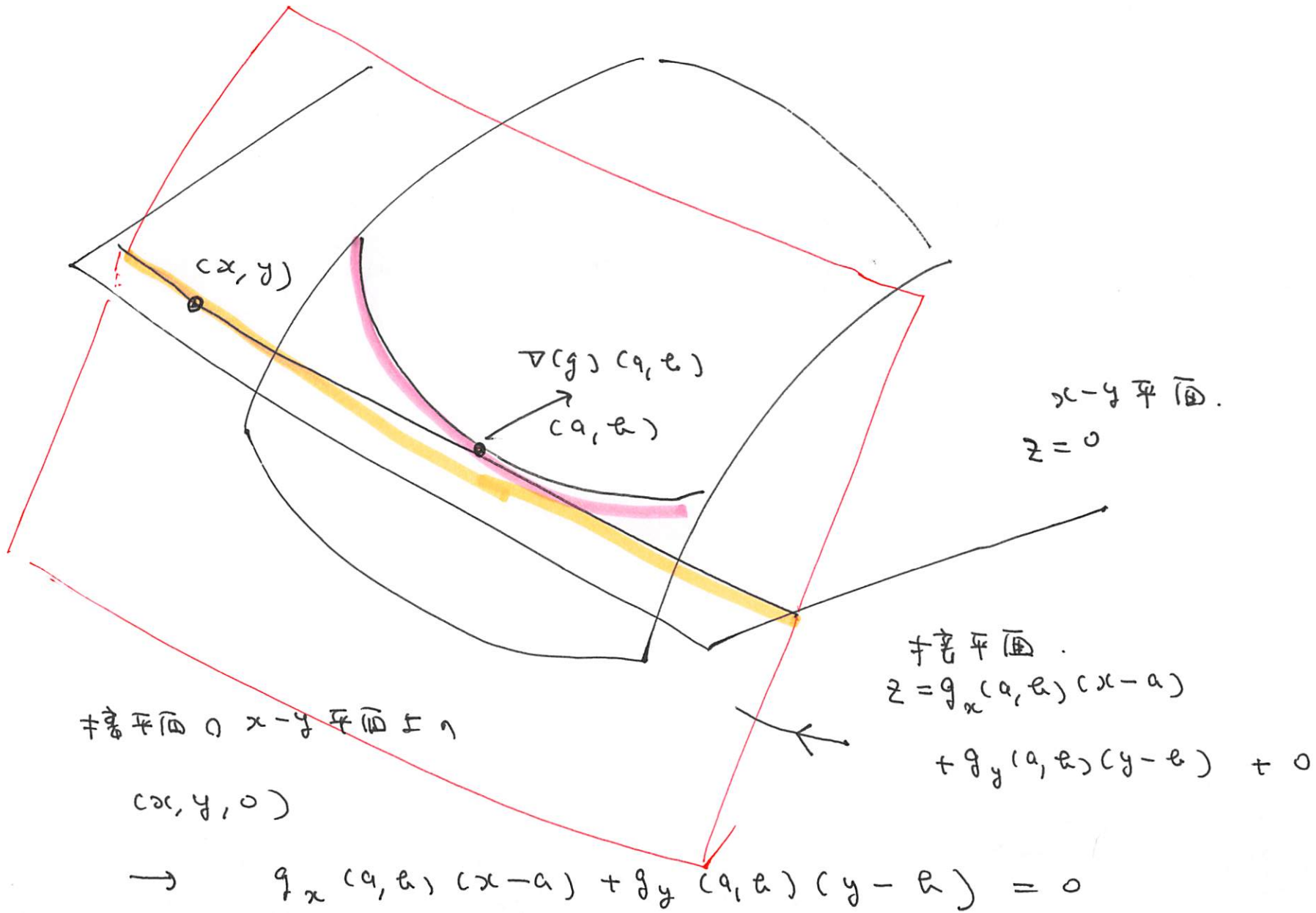
$$\begin{pmatrix} g_x(a, b) \\ g_y(a, b) \end{pmatrix} \cdot \begin{pmatrix} x-a \\ y-b \end{pmatrix} = 0$$

$$\nabla(g)(a, b) = \begin{pmatrix} g_x(a, b) \\ g_y(a, b) \end{pmatrix}$$



同法215111





$$I \quad x^2 - xy + y^2 - 1 = 0$$

$a(0, 1)$ となる場合系は \mathbb{C} である

$$II \quad z = x^2 - 3xy + y^2 - 1 \quad a(1, 0, 0) \text{ となる}$$

場合平面

III $\vec{a}, \vec{b}, \vec{c}$ ($\vec{a}, \vec{b}, \vec{c}$ は w, e, b)

$$z = x^4 + y^4 + 2x^2 - 4xy + 2y^2 \quad a \text{ 停留点}$$

IV \vec{a}, \vec{b}

$$x^2 + 4xy + 2y^2 - 6x - 8y \quad \mathbb{C} \text{ 平行移動して}$$

簡単に.