

$$I (1) \quad z = x^2 - xy + y^2 - 2x + 4y. \quad \text{9 } \frac{1}{3} \text{ 9 } \frac{1}{3} \text{ 點.}$$

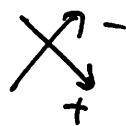
$$z_x = z_y = 0 \text{ 9 點.}$$

$$\begin{aligned} z_x &= 2x - y \cdot 1 + 0 - 2 + 0 \\ &= 2x - y - 2 = 0 \end{aligned}$$

$$\begin{aligned} z_y &= 0 - x \cdot 1 + 2y - 0 + 4 \\ &= -x + 2y + 4 = 0 \end{aligned}$$

$$z_x = z_y = 0 \iff \begin{cases} 2x - y = 2 \\ -x + 2y = -4. \end{cases}$$

$$D = \begin{vmatrix} 2 & -1 \\ -1 & 2 \end{vmatrix} = 4 - 1 = 3 \neq 0$$



$$x = \frac{1}{3} \begin{vmatrix} 2 & -1 \\ -4 & 2 \end{vmatrix} = 0$$

$$\left(\begin{matrix} 2 \\ -4 \end{matrix} \right) \parallel \left(\begin{matrix} -1 \\ 2 \end{matrix} \right)$$

$$y = \frac{1}{3} \begin{vmatrix} 2 & 2 \\ -1 & -4 \end{vmatrix} = \frac{1}{3} (-8 + 2) = -2$$

$$\frac{1}{3} \text{ 9 } \frac{1}{3} \text{ 點. (7) } (x, y) = (0, -2)$$

$$\begin{cases} ax + by = d \\ cx + dy = \beta. \end{cases}$$

$$\begin{aligned} D &= \begin{vmatrix} a & b \\ c & d \end{vmatrix} \neq 0 \\ &= ad - bc \end{aligned}$$

$$\begin{cases} x = \frac{1}{D} \begin{vmatrix} d & b \\ \beta & d \end{vmatrix} \\ y = \frac{1}{D} \begin{vmatrix} a & d \\ c & \beta \end{vmatrix} \end{cases}$$

$$(2) \quad z = \frac{1}{x^2 + y^2}$$

$$z_x = - \frac{1}{(x^2 + y^2)^2} \cdot 2x$$

$$= - \frac{2x}{(x^2 + y^2)^2}$$

$$z_y = - \frac{2y}{(x^2 + y^2)^2}$$

$$u = x^2 + y^2 \text{ et } z' = z$$

$$z = \frac{1}{u}$$

$$\left(\frac{1}{u}\right)' = - \frac{1}{u^2}$$

II (1)

$$\left(\begin{pmatrix} a & c \\ c & e \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) = \left(\begin{pmatrix} ax + cy \\ cx + ey \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right)$$

$$= (ax + cy)x + (cx + ey)y$$

$$= ax^2 + cxy + cxy + ey^2$$

$$= ax^2 + \underline{2c}xy + ey^2$$

$$\leftarrow A = \begin{pmatrix} a & c \\ c & e \end{pmatrix} \text{ or}$$

定数 $2 = 2 \times 1 \times 1$

$$z = x^2 - xy + y^2 - 2x + 4y$$

$\leftarrow x, y \text{ の } 2 = 2 \times 1 \times 1$

$$= \left(\begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + \underbrace{\begin{pmatrix} -2 & 4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}}_{\begin{pmatrix} -2 \\ 4 \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix}}$$

$$(a_1, a_2, \dots, a_n) \begin{pmatrix} e_1 \\ \vdots \\ e_n \end{pmatrix} = a_1 e_1 + a_2 e_2 + \dots + a_n e_n$$

$$\left(\begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}, \begin{pmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{pmatrix} \right)$$

$$\vec{a}, \vec{e} \in \mathbb{R}^n \quad \tau \vec{a} \vec{e} = (\vec{a}, \vec{e})$$

$$\vec{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} \rightsquigarrow \tau \vec{a} = (a_1, a_2, \dots, a_n)$$

$$A = \begin{pmatrix} a & c \\ c & b \end{pmatrix} \text{ 2x2 矩阵.}$$

$$\tau \begin{pmatrix} a & c \\ c & b \end{pmatrix} = \begin{pmatrix} a & c \\ c & b \end{pmatrix}$$

$$\tau A = A.$$

- 例 2

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \rightsquigarrow \tau A = \begin{pmatrix} a & c \\ b & d \end{pmatrix}$$

$$(2) \begin{pmatrix} d & -e \\ -c & a \end{pmatrix} \begin{pmatrix} a & e \\ c & d \end{pmatrix} = \begin{pmatrix} ad - ec & 0 \\ 0 & ad - ec \end{pmatrix} = |A| \cdot I_2$$

$$A = \begin{pmatrix} a & e \\ c & d \end{pmatrix} \Rightarrow \exists J, \sim \quad |A| = ad - ec$$

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{pmatrix} a & e \\ c & d \end{pmatrix} \begin{pmatrix} d & -e \\ -c & a \end{pmatrix} = \begin{pmatrix} ad - ec & 0 \\ 0 & ad - ec \end{pmatrix} = |A| I_2$$

finden

$$\tilde{A} = \begin{pmatrix} d & -e \\ -c & a \end{pmatrix} \quad A \text{ 的 余因子 矩阵.}$$

$$A \tilde{A} = \tilde{A} A = |A| I_2$$

$$\rightarrow |A| \neq 0 \text{ 则 } \exists$$

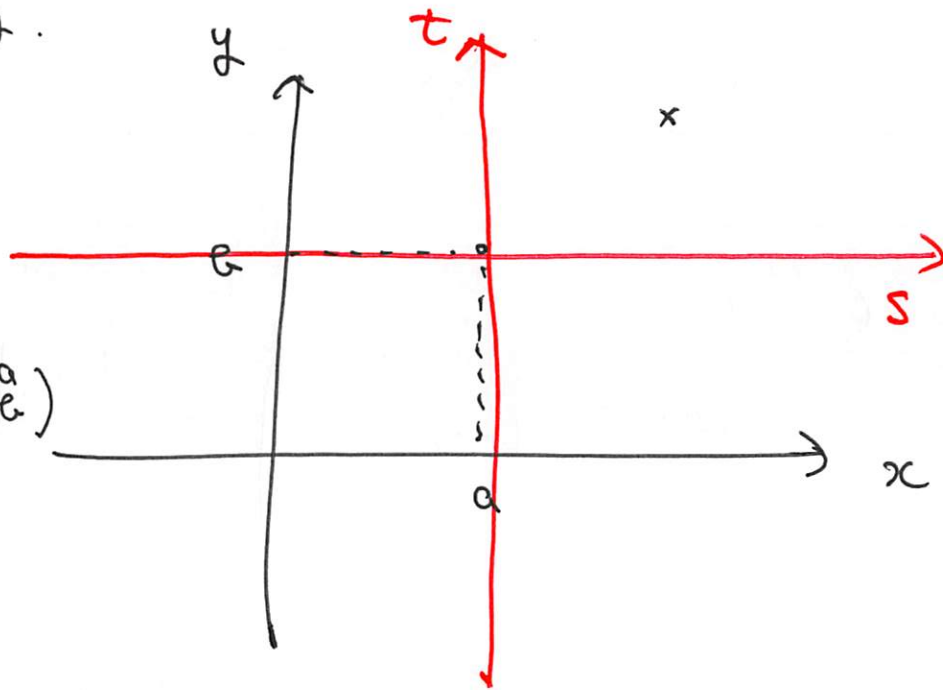
$$A \cdot \frac{1}{|A|} \tilde{A} = \frac{1}{|A|} \tilde{A} \cdot A = I_2$$

定理 $A: 2 \times 2 \quad |A| \neq 0 \Rightarrow A: \text{可逆}$

$$z = x^2 - xy + y^2 - 2x + 4y.$$

平行移動の座標変換

$$\begin{cases} s = x - a \\ t = y - b. \end{cases} \rightarrow \begin{pmatrix} s \\ t \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} a \\ b \end{pmatrix}$$



$$= \left(\begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + \left(\begin{pmatrix} -2 \\ 4 \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right)$$

$$a, b \text{ は } z \text{ の } \frac{\partial z}{\partial x} = 0 \text{ の } \begin{matrix} \rightarrow \\ \rightarrow \end{matrix} (a, b) = (0, -2) \text{ 停留点.}$$

$$= s^2 - 8t + t^2 - 4.$$

定理

$$A: 2 \times 2 \quad \vec{v}, \vec{w} \in \mathbb{R}^2 \quad A\vec{v} \in \mathbb{R}^2$$

$$(A\vec{v}, \vec{w}) = (\vec{v}, {}^t A \vec{w})$$

← 乘
(3).

$$\vec{r} = \begin{pmatrix} x \\ y \end{pmatrix}, \quad \vec{z} = \begin{pmatrix} s \\ t \end{pmatrix}, \quad \vec{z}_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \rightarrow \begin{aligned} \vec{z} &= \vec{z} - \vec{z}_0 \\ \vec{z} &= \vec{z} + \vec{z}_0 \end{aligned}$$

$$A = \begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix}$$

$$\vec{\beta} = \begin{pmatrix} -2 \\ 4 \end{pmatrix}$$

$$z = (A \vec{u}, \vec{u}) + (\vec{\beta}, \vec{z})$$

$$= (A(\vec{w} + \vec{v}_0), \vec{w} + \vec{v}_0) + (\vec{\beta}, \vec{z} + \vec{z}_0)$$

$$= A\vec{w} + A\vec{v}_0$$

$$= (A\vec{w}, \vec{w}) + (A\vec{w}, \vec{v}_0) + (A\vec{v}_0, \vec{w}) + (A\vec{v}_0, \vec{v}_0)$$

$$\begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix}$$

$$= A: \text{transp.}$$

$${}^t A = A$$

$$= (\vec{w}, {}^t A \vec{v}_0)$$

$$= (\vec{w}, A \vec{v}_0)$$

$$= (A \vec{v}_0, \vec{w})$$

$$+ (\vec{\beta}, \vec{w}) + (\vec{\beta}, \vec{z}_0)$$

$$= (A \vec{w}, \vec{w}) + 2 (A \vec{v}_0, \vec{w}) + (A \vec{v}_0, \vec{v}_0) + (\vec{\beta}, \vec{w}) + (\vec{\beta}, \vec{v}_0)$$

$$= (A \vec{w}, \vec{w}) + (2A\vec{v}_0 + \vec{\beta}, \vec{w}) + (A\vec{v}_0, \vec{v}_0) + (\vec{\beta}, \vec{v}_0)$$

$$\left(\begin{pmatrix} * \\ * \end{pmatrix}, \begin{pmatrix} s \\ t \end{pmatrix} \right) = *s + *t$$

$$= s^2 - st + t^2$$

$$a_1, a_2 \begin{pmatrix} 2 \\ -1 \end{pmatrix} \cdot \vec{v}_0 = \begin{pmatrix} a \\ b \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & -1 \\ 1 & 2 \end{pmatrix}$$

$$2A\vec{v}_0 + \vec{\beta} = \vec{0}$$

$$\Leftrightarrow \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} + \begin{pmatrix} -2 \\ 4 \end{pmatrix} = \vec{0} \Leftrightarrow \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ -2 \end{pmatrix}$$

$$z = \left(\begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} s \\ t \end{pmatrix}, \begin{pmatrix} s \\ t \end{pmatrix} \right) + \left(\begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 0 \\ -2 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \end{pmatrix} \right) + \left(\begin{pmatrix} -2 \\ 4 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \end{pmatrix} \right)$$

$$z = \left(\begin{pmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + \left(\begin{pmatrix} -2 \\ 4 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \end{pmatrix} \right)$$

$$\text{"}$$

$$z(x=0, y=-2)$$

$$= x^2 - xy + y^2 - 2x + 4y$$

$$z = s^2 - st + t^2 - 4.$$

平面上 \mathbb{R}^2 の二次形式 z を考える。

10.

$$A = \begin{pmatrix} a & c \\ c & e \end{pmatrix}, \quad \vec{\beta} = \begin{pmatrix} d \\ e \end{pmatrix}$$

$$|A| \neq 0$$

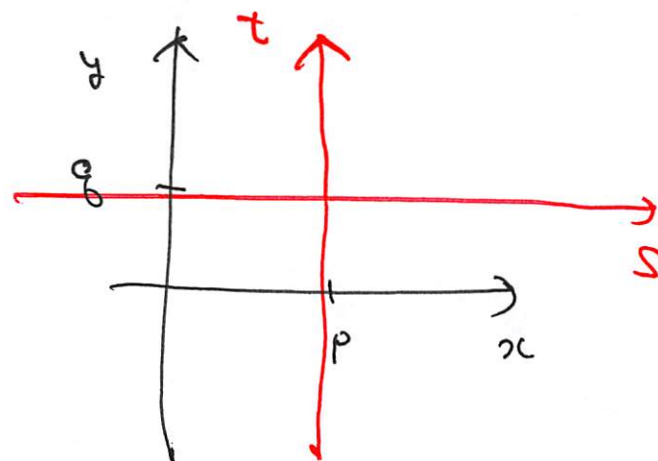
$$z = \left(A \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + \left(\vec{\beta}, \begin{pmatrix} x \\ y \end{pmatrix} \right) + f$$

$$= ax^2 + 2cxy + ey^2 + dx + ey + f.$$

$$\begin{pmatrix} s \\ t \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} p \\ q \end{pmatrix} \quad \text{t'z}$$

$$z = \left(A \begin{pmatrix} s \\ t \end{pmatrix}, \begin{pmatrix} s \\ t \end{pmatrix} \right) + f'$$

$$= as^2 + 2cst + et^2 + f'$$



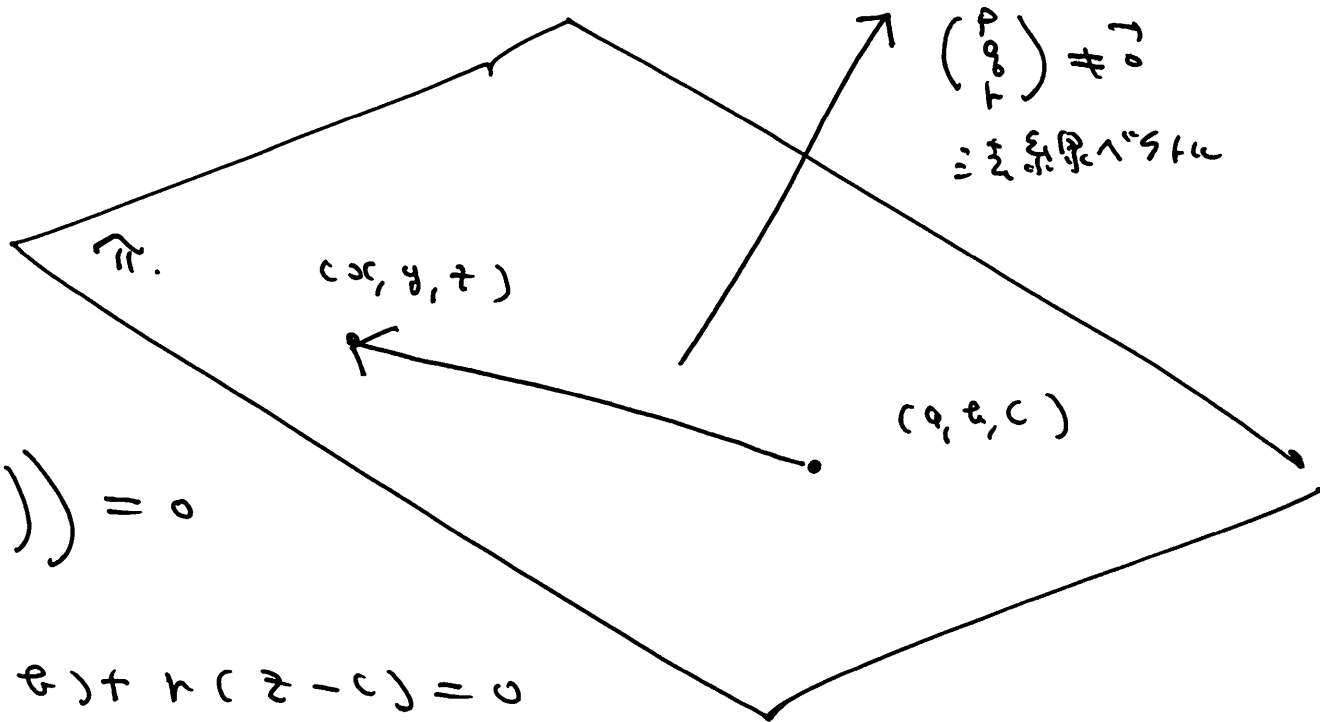
(12) C

$$2 A \begin{pmatrix} p \\ q \end{pmatrix} + \vec{\beta} = \vec{0}$$

$$f' = f + \left(A \begin{pmatrix} p \\ q \end{pmatrix}, \begin{pmatrix} p \\ q \end{pmatrix} \right) + \left(\vec{\beta}, \begin{pmatrix} p \\ q \end{pmatrix} \right)$$

$$= z(x=p, y=q)$$

平面 plane.



$$\begin{pmatrix} x-a \\ y-b \\ z-c \end{pmatrix}, \begin{pmatrix} p \\ q \\ r \end{pmatrix} = 0$$

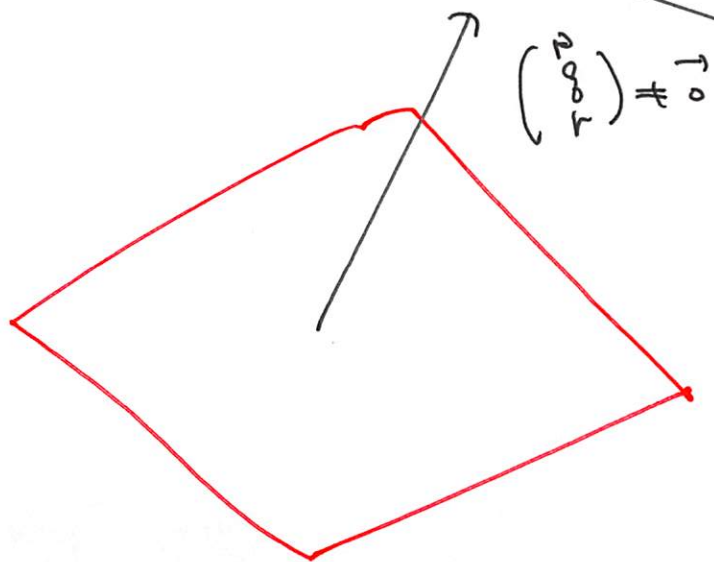
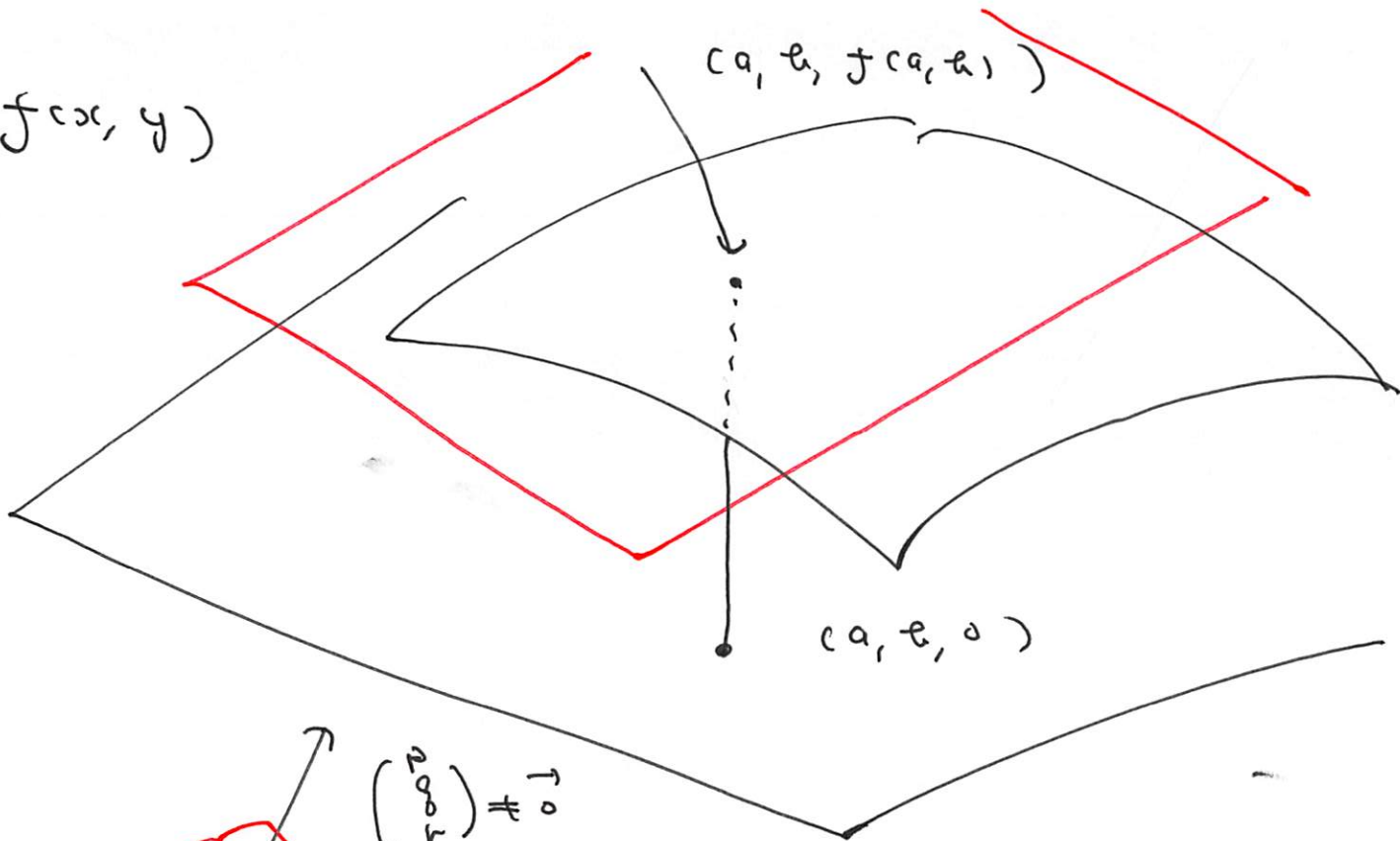
$$p(x-a) + q(y-b) + r(z-c) = 0$$

$$r \neq 0 \quad a < z$$

$$z = -\frac{p}{r}(x-a) - \frac{q}{r}(y-b) + c$$

$$= A(x-a) + B(y-b) + c \quad \text{と書ける.}$$

$$z = f(x, y)$$

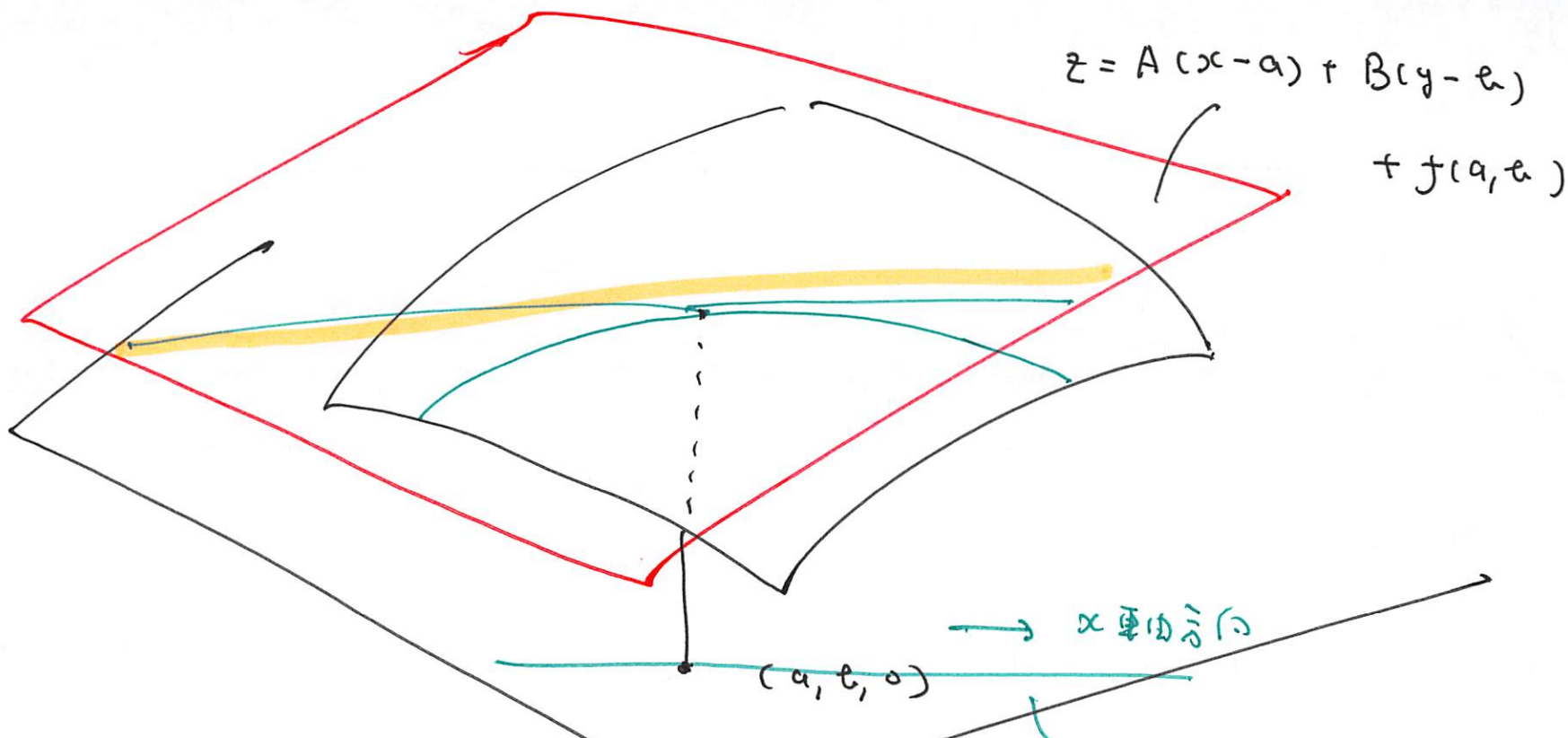


$r \neq 0$ に注意

$$\begin{pmatrix} p \\ q \\ 0 \end{pmatrix} \parallel x-y \text{ 平面}$$

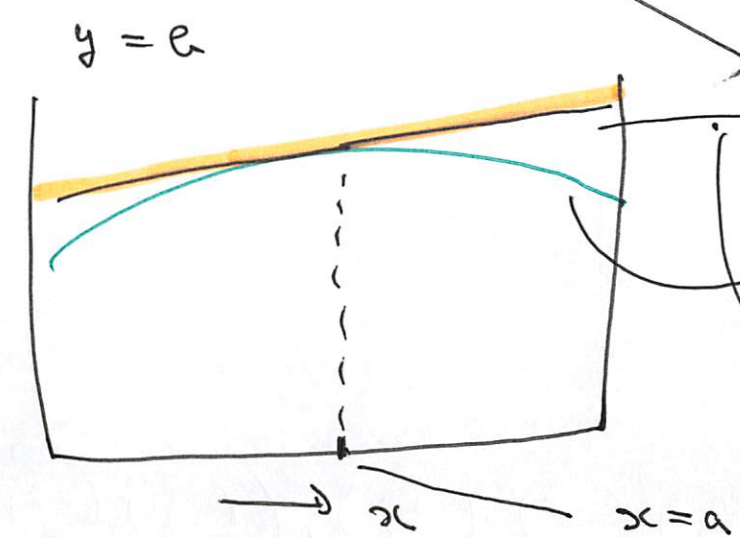
$$\begin{pmatrix} p \\ q \\ 0 \end{pmatrix} \perp \text{ 垂直な平面 } \perp x-y \text{ 平面}$$

$$z = A(x-a) + B(y-b) + f(a, b)$$



$$z = A(x-a) + B(y-b) + f(a, b)$$

→ x 軸の方向
y = b



y = b

接線の傾き $F'(a) = f_x(a, b)$

$$z = F(x) = f(x, b)$$

$$z = A(x-a) + f(a, b)$$

傾き A

$$A = F'(a) = f_x(a, b)$$

同様に y 軸方向に $\partial z / \partial y = f_y(a, b)$

手紙 $(a, b, f(a, b))$ は x 軸方向の接平面

$$z = f_x(a, b)(x - a) + f_y(a, b)(y - b) + f(a, b)$$

(1) $z = f(x, y) = x^2 - xy + y^2$ $(x, y, z) = (1, 1, 1)$
は x 軸方向の接平面