

$A = \begin{pmatrix} 1 & -4 & 2 \\ -4 & 7 & -4 \\ 2 & -4 & 1 \end{pmatrix} \leftarrow \text{symmetric}$

$$\Phi_A(\lambda) := |\lambda I_3 - A| = (\lambda + 1)^2 (\lambda - 11)$$

$$V(-1) = \ker(-I_3 - A)$$

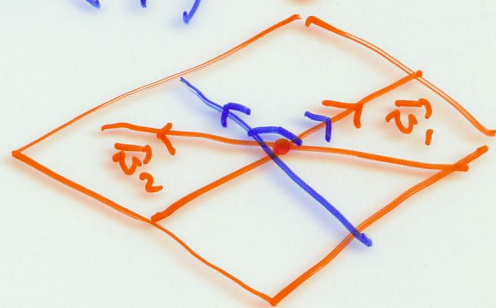
$$-I_3 - A = \begin{pmatrix} -2 & 4 & -2 \\ 4 & -8 & 4 \\ -2 & 4 & -2 \end{pmatrix} \rightarrow \dots \rightarrow \begin{pmatrix} 1 & -2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$0x + 0y + 0z = 0$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in V(-1) \Leftrightarrow x - 2y + z = 0$$

$$= \begin{pmatrix} 2y - z \\ y \\ z \end{pmatrix} = y \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$(\vec{v}_1, \vec{v}_2) = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = -2 \neq 0$$



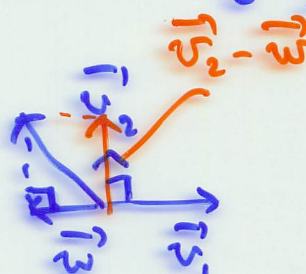
$$\vec{p}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{\sqrt{5}} \vec{v}_1 = \frac{1}{\sqrt{5}} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}$$

$$\vec{v}_2 \text{ and } \vec{v}_1 \text{ are not orthogonal}$$

$$\vec{e}_3 = \frac{(\vec{v}_1, \vec{v}_2)}{\|\vec{v}_1\|^2} \vec{v}_1 = \frac{-2}{5} \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -4/5 \\ -2/5 \\ 0 \end{pmatrix}$$

$$\vec{v}_2, \vec{e}_3 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -4/5 \\ -2/5 \\ 0 \end{pmatrix} = \frac{4}{5}$$

$$\vec{e}_2 = \frac{1}{\sqrt{1 - (4/5)^2}} \left(\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} - \frac{4}{5} \begin{pmatrix} -4/5 \\ -2/5 \\ 0 \end{pmatrix} \right) = \frac{1}{\sqrt{9/25}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = \frac{5}{3} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$



$\vec{e}_1 \in \vec{a} \neq \vec{0} \Rightarrow \vec{a} \perp \vec{e}_1$ 正射影是 \vec{a}

$$\vec{z} = \frac{(\vec{e}_1, \vec{e}_1)}{\|\vec{a}\|^2} \vec{a}$$

$V(-1) \quad \vec{p}_1, \vec{p}_2$

z : pivot $\neq 0$

$V(1) \quad \|I_3 - A \rightarrow \dots \rightarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$

pivot = 1

pivot $\neq 0$

$$\begin{cases} x - z = 0 \\ y + 2z = 0 \end{cases}$$

$z = \alpha \in \mathbb{R}$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \alpha \\ -2\alpha \\ \alpha \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$$

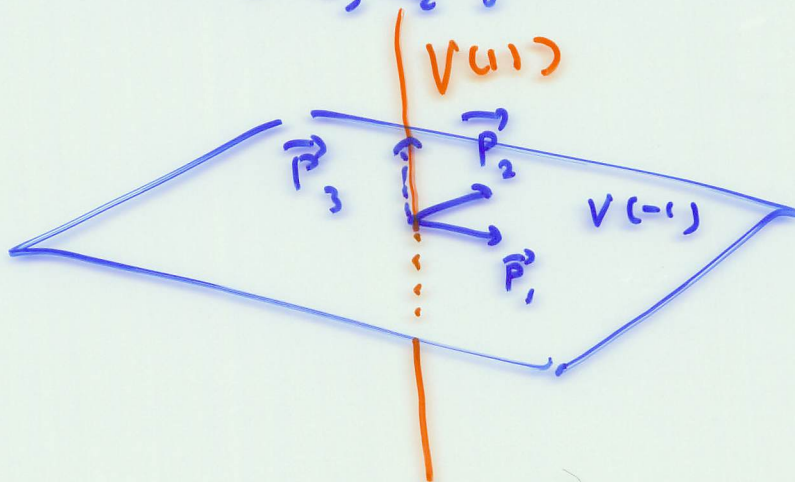
$$\vec{p}_3 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$$

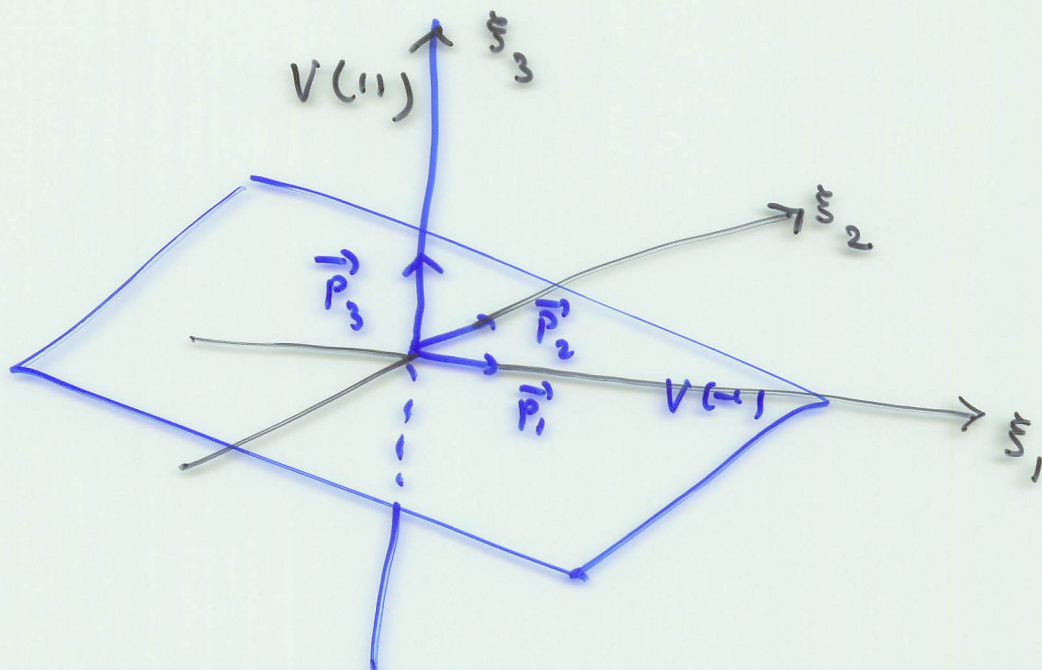
何故? $(\vec{p}_1, \vec{p}_3) = (\vec{p}_2, \vec{p}_3) = 0$

定理 A : 正射影, $\alpha, \beta: A \in \mathbb{R}$ 有 $\alpha \neq \beta$.

$$A\vec{v}_1 = \alpha\vec{v}_1, \quad A\vec{v}_2 = \beta\vec{v}_2$$

$$\leadsto (\vec{v}_1, \vec{v}_2) = 0$$





$$\vec{x} = (\vec{p}_1, \vec{p}_2, \vec{p}_3) \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} \rightsquigarrow \boxed{\begin{aligned} \vec{x} &= P \vec{\xi} \\ {}^t P \vec{x} &= \vec{\xi} \end{aligned}}$$

$$= \xi_1 \vec{p}_1 + \xi_2 \vec{p}_2 + \xi_3 \vec{p}_3$$

I_3

$$(A \vec{x}, \vec{x}) = ({}^t P A P {}^t P \vec{x}, {}^t P \vec{x})$$

$${}^t P: \mathbb{R}^3 \leftarrow$$

$$P: \mathbb{R}^3 \rightarrow$$

$${}^t P P = P {}^t P = I_3$$

$$\rightsquigarrow {}^t P ({}^t ({}^t P))$$

$${}^t ({}^t P) = P$$

$$= {}^t ({}^t P) {}^t P = I_3$$

$$(P \vec{x}, P \vec{y}) = (\vec{x}, \vec{y})$$

$${}^t P A P = \begin{pmatrix} -1 & & \\ & -1 & \\ & & 11 \end{pmatrix}, \quad {}^t P \vec{x} = \vec{\xi}$$

$$= \left(\begin{pmatrix} -1 & & \\ & -1 & \\ & & 11 \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix}, \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} \right)$$

$$= -\xi_1^2 - \xi_2^2 + 11\xi_3^2$$

A: 対称行列 (n=2)
実

① A の固有値は全て実

$$\Phi_A(\lambda) = (\lambda - \alpha_1)(\lambda - \alpha_2) \cdots (\lambda - \alpha_n)$$

$$\alpha_1, \dots, \alpha_n \in \mathbb{R}.$$

② 直交行列 P 存在

$$AP = P \begin{pmatrix} \alpha_1 & & \\ & \ddots & \\ & & \alpha_n \end{pmatrix}$$

$$P^T P = I_n$$

$$A = P \begin{pmatrix} \alpha_1 & & \\ & \ddots & \\ & & \alpha_n \end{pmatrix} P^T$$

$$P^{-1} = P^T$$

$$AP = P \begin{pmatrix} -1 & \\ & -1 \end{pmatrix}$$

P: 直交

2次元空間

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$(A\vec{x}, \vec{x})$$

$$A = \begin{pmatrix} 1 & -4 & 2 \\ -4 & 7 & -4 \\ 2 & -4 & 1 \end{pmatrix}$$

$$\left(A \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = \begin{pmatrix} x - 4y + 2z \\ -4x + 7y - 4z \\ 2x - 4y + z \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$= x^2 + 7y^2 + z^2$$

$$+ 8xy - 8yz + 4xz.$$

$$w = f(x, y, z)$$

定理 w on $(x, y, z) = (a, b, c)$ 2nd order.
or 2nd order

$$\Rightarrow \textcircled{\#} \frac{\partial f}{\partial x}(a, b, c) = \frac{\partial f}{\partial y}(a, b, c) = \frac{\partial f}{\partial z}(a, b, c) = 0$$

i.e. (a, b, c) is a stationary point.
is also

$$F(x) = f(x, a, b) \text{ on } x = a \text{ is stationary. } (x)$$

$$\leadsto F'(a) = f_x(a, b, c) = 0.$$

定理 $\textcircled{\#}$ is valid. f is C^2 and is valid.

$$H(f) = \begin{pmatrix} f_{xx} & f_{xy} & f_{xz} \\ f_{yx} & f_{yy} & f_{yz} \\ f_{zx} & f_{zy} & f_{zz} \end{pmatrix}$$



valid.

valid.

$$f_{xy} = f_{yx}$$

$$(H(f)(a, b, c) \vec{v}, \vec{v}) \begin{matrix} < \\ > \end{matrix} 0 \quad (\vec{v} \neq \vec{0})$$

$$\rightarrow (a, b, c) \text{ is stationary.}$$

is also valid.

A: valid.

$$(A \vec{x}, \vec{x}) > 0 \quad (\vec{x} \neq 0) : \text{2nd order is valid.}$$

< 0

is.

$$A = \begin{pmatrix} a & c \\ c & b \end{pmatrix} \quad \text{实对称.}$$

$$\begin{aligned} \begin{vmatrix} \lambda - a & -c \\ -c & \lambda - b \end{vmatrix} &= (\lambda - a)(\lambda - b) - c^2 \\ &= \lambda^2 - (a+b)\lambda + ab - c^2 = 0 \end{aligned}$$

$$\begin{aligned} D &= (a+b)^2 - 4(ab - c^2) \\ &= (a-b)^2 + 4c^2 \geq 0 \end{aligned}$$

$$D=0 \Leftrightarrow a=b, c=0$$

$$A = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} = aI_2.$$

固有值 α, β

定理 $(A\vec{x}, \vec{x})$: 正定值. (负定值)

$$\Leftrightarrow \begin{array}{l} \alpha, \beta > 0 \\ < 0 \end{array} \Leftrightarrow \begin{array}{l} a > 0, |A| > 0 \\ a < 0, |A| > 0. \end{array}$$

$$(A\vec{x}, \vec{x}) < 0 \quad (\vec{x} \neq \vec{0})$$

$$AP = P(\alpha, \beta) \quad P: \text{正交}$$

$$(A\vec{x}, \vec{x}) = (\underbrace{P^T A P}_{= I_2} \underbrace{P^T \vec{x}}_{\vec{y}}, \underbrace{P^T \vec{x}}_{\vec{y}})$$

$$= \left(\begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \right)$$

$$= \alpha y_1^2 + \beta y_2^2$$

$$P^T \vec{x} = \vec{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\vec{x} \neq \vec{0}$$

$$\Leftrightarrow \vec{y} \neq \vec{0}$$

$$(A\vec{x}, \vec{x}) > 0 \quad (\vec{x} \neq \vec{0})$$



$$\alpha y_1^2 + \beta y_2^2 > 0 \quad \left(\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \neq \vec{0} \right)$$

P : 正交

$$\star \alpha x_1^2 + \beta x_2^2 > 0 \quad \left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right)$$

\Leftrightarrow

$$\alpha, \beta > 0$$

$$(i) \quad \alpha, \beta > 0 \in \mathbb{R}.$$

$$\alpha x_1^2 + \beta x_2^2 \geq 0$$

$\rightarrow 0.$

\rightarrow 正定 (★)

$$x_1 \neq 0 \rightarrow \alpha x_1^2 > 0$$

$$x_2 \neq 0 \rightarrow \beta x_2^2 > 0$$

$$(ii) \quad \star \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightarrow \alpha > 0$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \rightarrow \beta > 0$$

$$\alpha, \beta > 0 \Leftrightarrow \alpha + \beta > 0, \alpha\beta > 0$$

$$\lambda^2 - (\alpha + \beta)\lambda + \alpha\beta = \lambda^2 - (a+b)\lambda + |A|$$

$$\boxed{\alpha\beta = |A|, \quad \alpha + \beta = a + b.}$$

$$A = \begin{pmatrix} a & c \\ c & b \end{pmatrix}$$

$$(i) \quad \alpha + \beta > 0, \quad \alpha\beta > 0 \rightarrow |A| > 0$$

\Downarrow

$$|A| = ab - c^2 \leq ab$$

$$\rightarrow ab > 0, a+b > 0$$

$$\rightarrow a, b > 0 \rightarrow a > 0$$



$$(ii) \quad \alpha > 0, \quad |A| > 0$$

\Downarrow

$$\alpha\beta$$

$$ab - c^2$$

$$ab - c^2 > 0$$

$$ab > c^2 \geq 0$$

$$a > 0, ab > 0 \rightarrow b > 0$$

$$\rightarrow ab > 0$$

$$\alpha + \beta = a + b > 0.$$

$$\alpha\beta > 0, \alpha + \beta > 0.$$

定理 $f_x(a, b) = f_y(a, b) = 0$

$$f_{xx}(a, b) > 0, \quad \begin{vmatrix} f_{xx}(a, b) & f_{xy}(a, b) \\ f_{yx}(a, b) & f_{yy}(a, b) \end{vmatrix} > 0$$

$$\Rightarrow (a, b) \text{ 是 } f \text{ 的极小值点.} \quad (f_{yx}) = (f_{xy})_x$$

(i) $f(x, y) = x^3 + y^3 - 3xy$

求驻点并求极值

(ii) 求驻点并求极值. 求判定行列式.