

直交行列 $P: \mathbb{R}^n \rightarrow \mathbb{R}^n$ の

$$(P\vec{x}, P\vec{y}) = (\vec{x}, \vec{y})$$

$$\Leftrightarrow \|P\vec{x}\|^2 = \|\vec{x}\|^2$$

$$\Leftrightarrow {}^t P P = P {}^t P = I_n \quad \leadsto {}^t P = P^{-1}$$

$$\Leftrightarrow P = (\vec{p}_1 \dots \vec{p}_n)$$

$$(\vec{p}_i, \vec{p}_j) = \begin{cases} 1 & (i=j) \\ 0 & (i \neq j) \end{cases}$$

A : 実対称. ${}^t A = A$

$$A = (a_{ij}) \quad a_{ij} = a_{ji}$$

定理 A : 実対称. 直交行列 P により $P^{-1} A P = D$

$$A = P \begin{pmatrix} d_1 & & \\ & \ddots & \\ & & d_n \end{pmatrix} P^{-1}$$

対角化可能

$$d_1, \dots, d_n \in \mathbb{R}.$$

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\begin{aligned} \Phi_A(\lambda) &= |\lambda I_3 - A| = \begin{vmatrix} \lambda & 0 & -1 \\ 0 & \lambda+1 & 0 \\ -1 & 0 & \lambda \end{vmatrix} \\ &= (-1)^{2+2} (\lambda+1) \begin{vmatrix} \lambda & -1 \\ -1 & \lambda \end{vmatrix} \quad \begin{matrix} \text{234の余因} \\ \text{定理.} \end{matrix} \\ &= (\lambda+1)(\lambda^2-1) = (\lambda+1)^2(\lambda-1) \end{aligned}$$

$\lambda = -1$ $V(-1) = \ker(-I_3 - A)$

$$\begin{pmatrix} -1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & -1 \end{pmatrix} \rightarrow \dots \rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in V(-1) \iff \underline{x+z=0}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -z \\ y \\ z \end{pmatrix} = z \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} + y \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\vec{e}_1 = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \vec{e}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \rightsquigarrow \vec{e}_1 \perp \vec{e}_2$$

$$\vec{p}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}, \vec{p}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$\lambda = 1$ $\begin{pmatrix} \textcircled{1} & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \in V(1) \iff x=z, y=0$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ 0 \\ z \end{pmatrix} = z \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$\vec{p}_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

定理 A : 行列, $\alpha, \beta \in \mathbb{R}$ 固有値.

$$A \vec{v}_1 = \alpha \vec{v}_1, \quad A \vec{v}_2 = \beta \vec{v}_2$$

$$\alpha \neq \beta \quad \Rightarrow \quad (\vec{v}_1, \vec{v}_2) = 0$$

$$(\vec{p}_1, \vec{p}_3) = (\vec{p}_2, \vec{p}_3) = 0 \text{ である.}$$

$$\leadsto P = (\vec{p}_1 \ \vec{p}_2 \ \vec{p}_3) \text{ は 逆行列存在.}$$

$$A \vec{p}_1 = -\vec{p}_1, \quad A \vec{p}_2 = -\vec{p}_2, \quad A \vec{p}_3 = \vec{p}_3$$

$$AP = (-\vec{p}_1 \ -\vec{p}_2 \ \vec{p}_3) = (\vec{p}_1 \ \vec{p}_2 \ \vec{p}_3) \begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix}$$

$$= P \begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix} \leadsto A = P \begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix} {}^t P$$

$$\begin{aligned} {}^t P P &= I_3 \\ {}^t P &= P^{-1} \end{aligned}$$

定理の証明

$$(\alpha \vec{v}_1, \vec{v}_2) = (A \vec{v}_1, \vec{v}_2) = (\vec{v}_1, A \vec{v}_2)$$

$$\stackrel{=}{=} \alpha (\vec{v}_1, \vec{v}_2)$$

$$\stackrel{=}{=} (\vec{v}_1, \beta \vec{v}_2)$$

$$\stackrel{\neq}{=} (\alpha - \beta) (\vec{v}_1, \vec{v}_2) = 0$$

$$\stackrel{=}{=} \beta (\vec{v}_1, \vec{v}_2)$$

$$\leadsto (\vec{v}_1, \vec{v}_2) = 0$$

x	y	z
x_1	y_1	z_1
x_2	y_2	z_2
$\vdots$	$\vdots$	$\vdots$
x_N	y_N	z_N

$$\vec{x} = \frac{1}{\sqrt{N}} \begin{pmatrix} x_1 - \bar{x} \\ x_2 - \bar{x} \\ \vdots \\ x_N - \bar{x} \end{pmatrix} \quad \vec{y}, \vec{z} \dots$$

$$\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$$

$$\|\vec{x}\|^2 = V(x) = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})^2$$

$$\begin{aligned} (\vec{x}, \vec{z}) &= \alpha_{xz} \quad \text{共分散} \\ &= \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})(z_i - \bar{z}) \end{aligned}$$

$$w = \alpha x + \beta y + \gamma z$$

$$\boxed{w_i = \alpha x_i + \beta y_i + \gamma z_i} \quad i=1, \dots, N.$$

$$\bar{w} = \alpha \bar{x} + \beta \bar{y} + \gamma \bar{z}$$

$$\frac{1}{\sqrt{N}}(w_i - \bar{w}) = \frac{\alpha}{\sqrt{N}}(x_i - \bar{x}) + \frac{\beta}{\sqrt{N}}(y_i - \bar{y}) + \frac{\gamma}{\sqrt{N}}(z_i - \bar{z})$$

$$\vec{w} = \alpha \vec{x} + \beta \vec{y} + \gamma \vec{z} = (\vec{x} \ \vec{y} \ \vec{z}) \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

$\vec{w}$ の 1 次元基底

$$D = (\vec{x} \ \vec{y} \ \vec{z}) \in \mathbb{R}^N$$

$$\begin{aligned} \|\vec{w}\|^2 &= (D \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}, D \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}) \\ &= ({}^t D D \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}, \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}). \end{aligned}$$

$V(w)$ は ${}^t D D$ の 2 次元固有値.

$$D = (\vec{x} \quad \vec{y} \quad \vec{z})$$

$${}^t D D = \begin{pmatrix} {}^t \vec{x} \\ {}^t \vec{y} \\ {}^t \vec{z} \end{pmatrix} (\vec{x} \quad \vec{y} \quad \vec{z})$$

$$= \begin{pmatrix} {}^t \vec{x} \vec{x} & {}^t \vec{x} \vec{y} & {}^t \vec{x} \vec{z} \\ {}^t \vec{y} \vec{x} & {}^t \vec{y} \vec{y} & {}^t \vec{y} \vec{z} \\ {}^t \vec{z} \vec{x} & {}^t \vec{z} \vec{y} & {}^t \vec{z} \vec{z} \end{pmatrix}$$

$$= \begin{pmatrix} V(x) & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & V(y) & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & V(z) \end{pmatrix} \quad (\vec{a}, \vec{e}) = {}^t \vec{a} \vec{e}$$

विशेषता

$$({}^t D D)^t = {}^t D {}^t ({}^t D)$$

$$= {}^t D D$$

$\leadsto {}^t D D : \text{सममित}$

$$\begin{cases} {}^t (AB) = {}^t B {}^t A \\ {}^t ({}^t A) = A \end{cases}$$

$$\alpha^2 + \beta^2 + \gamma^2 = 1 \text{ अतः } \|\vec{w}\|^2 = \sum_{i=1}^3 x_i^2 \cdot \sum_{i=1}^3 y_i^2$$

$V(w)$

सममित

$$\vec{v} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$(A\vec{v}, \vec{v}) = \left(\begin{pmatrix} 0 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right)$$

$$= \left(\begin{pmatrix} z \\ -y \\ x \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = -y^2 + xz$$

A 0... ~~is~~ 2 = $\mathbb{R}^3$ $\mathbb{R}^3$.

$$P: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

$${}^t P P = I_3$$

$$P {}^t P = I_3$$

$$(A\vec{v}, \vec{v}) = ({}^t P A \vec{v}, {}^t P \vec{v})$$

$$P {}^t P$$

$${}^t P A P = \begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix}$$

$$= \left(\begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix} {}^t P \vec{v}, {}^t P \vec{v} \right)$$

$${}^t P \vec{v} = I_3 \vec{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \quad \left(\begin{pmatrix} -1 & & \\ & -1 & \\ & & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}, \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \right)$$

$$= \begin{pmatrix} -v_1 \\ -v_2 \\ v_3 \end{pmatrix} \cdot \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

$$= -v_1^2 - v_2^2 + v_3^2$$

$$A = \begin{pmatrix} 1 & -4 & 2 \\ -4 & 7 & -4 \\ 2 & -4 & 1 \end{pmatrix}$$

Σ 17 34 2 37 10 33.
