

$$\begin{array}{c|cc|c} x & y & z \\ \hline x_1 & y_1 & z_1 \\ \vdots & \vdots & \vdots \\ x_N & y_N & z_N \end{array}$$

$$\vec{x} = \frac{1}{\sqrt{N}} \begin{pmatrix} x_1 - \bar{x} \\ \vdots \\ x_N - \bar{x} \end{pmatrix} \quad V(x) = \|\vec{x}\|^2$$

$\vec{x}, \vec{y}, \vec{z}$ : フラットベクトル

$$\vec{w} = \alpha \vec{x} + \beta \vec{y} + \gamma \vec{z}$$

$\alpha, \beta, \gamma$ : 定数

$$\vec{\omega} = \frac{1}{\sqrt{N}} \begin{pmatrix} w_1 - \bar{w} \\ \vdots \\ w_N - \bar{w} \end{pmatrix} = \alpha \vec{x} + \beta \vec{y} + \gamma \vec{z}$$

$$w_i = \alpha x_i + \beta y_i + \gamma z_i$$

$$\underbrace{\bar{w} = \alpha \bar{x} + \beta \bar{y} + \gamma \bar{z}}$$

$$w_i - \bar{w} = \alpha (x_i - \bar{x}) + \beta (y_i - \bar{y}) + \gamma (z_i - \bar{z})$$

$$\vec{w} = \alpha \vec{x} + \beta \vec{y} + \gamma \vec{z}$$

$$= (\vec{x} \ \vec{y} \ \vec{z}) \vec{\alpha}$$

$$\vec{\alpha} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

$$V(w) = \|\vec{w}\|^2 \quad \boxed{= D \vec{\alpha}}$$

$$= (D \vec{\alpha}, D \vec{\alpha})$$

$$(D \vec{\alpha}, D \vec{\alpha}) = \|D \vec{\alpha}\|^2$$

公式

$$= (D^T D \vec{\alpha}, \vec{\alpha})$$

$$= \vec{\alpha}^T \vec{\alpha}$$

$$= \|\vec{x}\|^2$$

$$= V(x)$$

$$+ \vec{y}^T \vec{x} = (\vec{y}, \vec{x})$$

$$= \sigma_{xy}$$

$$= \frac{1}{2} \sigma_{xy}^2$$

$$D^T D = \begin{pmatrix} \vec{x}^T \\ \vec{y}^T \\ \vec{z}^T \end{pmatrix} \begin{pmatrix} \vec{x} & \vec{y} & \vec{z} \end{pmatrix}$$

$$= \begin{pmatrix} V(x) & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & V(y) & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & V(z) \end{pmatrix}$$

$${}^t(tDD) = tD \cdot {}^t(tD) = tDD$$

$tDD$ : 斜对称.

$${}^t(AB) = {}^tB {}^tA$$

$tDD$ :  $D \otimes I^n$  的转置.

$$A = (a_{ij}) \quad a_{ij} = a_{ji} \quad \text{斜对称.}$$

$${}^t A = A$$

$$(A \vec{v}, \vec{v}) \quad A, \vec{v} \in \mathbb{R}^{n \times n}.$$

$$\underline{n=2} \quad A = \begin{pmatrix} a & c \\ c & b \end{pmatrix} \quad \text{斜对称.}$$

$$\bar{\Phi}_A(\lambda)$$

$$= \det(\lambda I_2 - A) = \begin{vmatrix} \lambda - a & -c \\ -c & \lambda - b \end{vmatrix}$$

$$= (\lambda - a)(\lambda - b) - c^2$$

$$= \lambda^2 - (a+b)\lambda + (ab - c^2)$$

$$D = (a+b)^2 - 4(ab - c^2)$$

$$= (a-b)^2 + 4c^2 \geq 0$$

- $\bar{\Phi}_A(\lambda)$  有 2 个 实根.

- $\bar{\Phi}_A(\lambda)$  有 2 个 实根  $\Leftrightarrow D = 0$

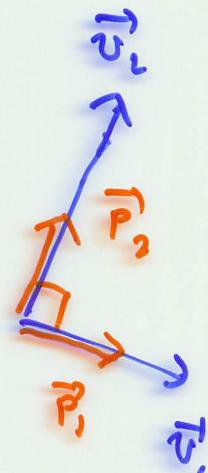
$$\Leftrightarrow a = b, c = 0$$

$$A = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} = a I_2$$

$$\vec{P}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1, \quad \vec{P}_2 = \frac{1}{\|\vec{v}_2\|} \vec{v}_2$$

$$\|\vec{P}_1\| = \|\vec{P}_2\| = 1, \quad (\vec{P}_1, \vec{P}_2) = 0$$

$$P = (\vec{P}_1, \vec{P}_2) : \text{直交}.$$



$$\begin{aligned} {}^t P P &= \begin{pmatrix} {}^t \vec{P}_1 \\ {}^t \vec{P}_2 \end{pmatrix} (\vec{P}_1, \vec{P}_2) \\ &= \begin{pmatrix} \|\vec{P}_1\|^2 & (\vec{P}_1, \vec{P}_2) \\ (\vec{P}_1, \vec{P}_2) & \|\vec{P}_2\|^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

$$\rightsquigarrow {}^t P P = I_2$$

$$\det({}^t P P) = \det(I_2) = 1$$

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$$\det({}^t P) \det(P) = \det(P)^2$$

$\det({}^t C) = \det(C)$

$$\rightsquigarrow \det(P) = \pm 1$$

$\neq 0$

$$\begin{aligned} {}^t P P &= I_2 \\ \cdot P^{-1} &\rightarrow {}^t P = P^{-1} \end{aligned}$$

$P^t P = I_2$

直交  $\Rightarrow {}^t P P = P^t P = I_2$

$$\frac{D > 0 \in \mathbb{R}^n}{(A = \alpha I_n, \text{ if } \lambda_1 = \dots = \lambda_n)} \longrightarrow \Phi_A(\lambda) = (\lambda - \alpha)(\lambda - \beta)$$

$\alpha \neq \beta.$

$$\begin{array}{l} \alpha \text{ 的固有值} \\ \beta \end{array} \xrightarrow{\vec{v}_1 \neq \vec{v}_2} \begin{array}{l} \vec{v}_1 \neq \vec{0} \\ A \vec{v}_1 = \alpha \vec{v}_1 \end{array}$$

$$\begin{array}{l} \vec{v}_2 \neq \vec{0} \\ A \vec{v}_2 = \beta \vec{v}_2 \end{array}$$


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$\vec{v}_1, \dots, \vec{v}_k$  线性无关

$A: -\text{方阵}, \text{对角化}$

$\alpha_i \neq \alpha_j \text{ 固有值}$

$A \vec{v}_i = \alpha_i \vec{v}_i \quad (i=1, \dots, k)$

$c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0}$

$\Rightarrow c_1 = c_2 = \dots = c_k = 0$

$\vec{v}_1, \dots, \vec{v}_k: \text{线性无关}$

定理  $(\vec{v}_1, \vec{v}_2) = 0.$

$$(A \vec{v}_1, \vec{v}_2) = (\vec{v}_1, A \vec{v}_2) = (\vec{v}_1, A \vec{v}_2)$$

$$(\alpha \vec{v}_1, \vec{v}_2)$$

" "

$$\alpha (\vec{v}_1, \vec{v}_2)$$

$$(\vec{v}_1, \beta \vec{v}_2)$$

" "

$$\beta (\vec{v}_1, \vec{v}_2)$$

$$\xrightarrow{\#} (\alpha - \beta) (\vec{v}_1, \vec{v}_2) = 0$$

$$\xrightarrow{\#} (\vec{v}_1, \vec{v}_2) = 0$$

$$A \vec{P}_1 = \alpha \vec{P}_1, \quad A \vec{P}_2 = \beta \vec{P}_2$$

$$A(\vec{P}_1 \vec{P}_2) = (\vec{P}_1 \vec{P}_2) \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}$$

$t_P A P = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}$        $P^{-1} = t_P$ .

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$A = P \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} t_P$

$t_P \in \text{直交}.$        $t_P \cdot t(t_P) = t_P P = I_2$

$t(t_P) t_P = P t_P = I.$

$t(t_P) t_P = t_P t(t_P) = I_2$

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$$(A \vec{v}, \vec{v}) = (\cancel{t_P A P \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} \vec{v}}, \vec{v})$$

$\rightarrow (P \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} t_P \vec{v}, \vec{v})$

$$= ((\alpha 0 \ 0 \beta) t_P \vec{v}, t_P \vec{v})$$

$t_P \vec{v} = \vec{\xi} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \quad \vec{v} = P \vec{\xi}$

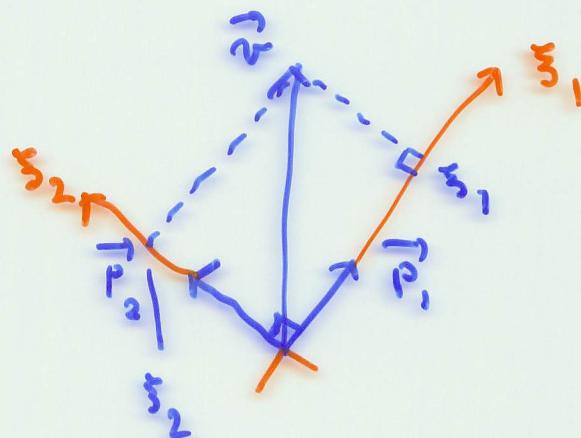
$$= ((\alpha 0 \ 0 \beta) \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}, \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix})$$

$$= \left( \begin{pmatrix} \alpha \xi_1 \\ \beta \xi_2 \end{pmatrix}, \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \right)$$

$$= \alpha \xi_1^2 + \beta \xi_2^2$$

$$\vec{v} = p \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = (\vec{p}_1, \vec{p}_2) \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}$$

$$= \xi_1 \vec{p}_1 + \xi_2 \vec{p}_2$$

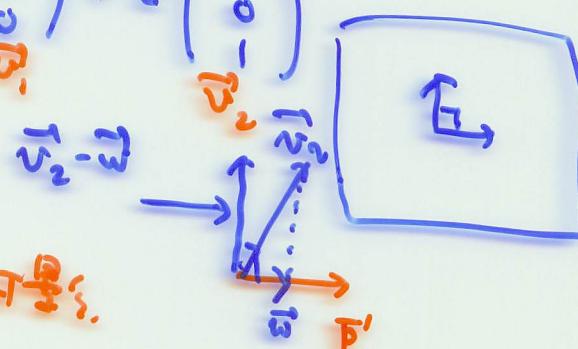


$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \quad \Phi_A(\lambda) = (\lambda - 1)^2(\lambda - 4)$$

$$\underline{V(1)} \quad I_3 - A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -y - z \\ y \\ z \end{pmatrix} = y \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad x + y + z = 0$$

$$\vec{p}_1 = \frac{1}{\|\vec{p}_1\|} \vec{v}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$



$\vec{w}$ :  $\vec{v}_2$  and  $\vec{p}_1$  is linearly independent.

$$\begin{aligned} &= \left( \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right) \cdot \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad \vec{p}_2 = \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix} \\ &= \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \end{aligned}$$

$$\vec{v}_2 - \vec{w} = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix}$$

$$\underline{V(4)} \quad 4I_3 - A = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} - \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix} \xrightarrow{\text{1} \leftrightarrow 3 \text{ r}} \begin{pmatrix} -1 & -1 & 2 \\ -1 & 2 & -1 \\ 2 & -1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix} \leftarrow \cdots \leftarrow \begin{pmatrix} 1 & 1 & -2 \\ 0 & 3 & -3 \\ 0 & -3 & 3 \end{pmatrix} \leftarrow \begin{pmatrix} 1 & 1 & -2 \\ -1 & 2 & -1 \\ 2 & -1 & 1 \end{pmatrix}$$

$$\downarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$x = 2 \\ y = 2$$

$$- \underline{\underline{2 \ 2 \ 2 \ -4}}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \vec{P}_3 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\|\vec{P}_1\| = \|\vec{P}_2\| = \|\vec{P}_3\| = 1$$

$$(\vec{P}_1, \vec{P}_2) = 0 \quad (\vec{P}_1, \vec{P}_3) = (\vec{P}_2, \vec{P}_3) = 0$$

定理  $A$ : 3x3 雅可布矩阵  $\alpha, \beta$  同符号  
 $\alpha \neq \beta$

$$A \vec{v}_1 = \alpha \vec{v}_1, \quad A \vec{v}_2 = \beta \vec{v}_2 \rightarrow (\vec{v}_1, \vec{v}_2) = 0$$

$$P = (\vec{p}_1 \vec{p}_2 \vec{p}_3)$$

$$t_{PP} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \rightarrow t_P = P^{-1} \\ P^t P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$AP = P \begin{pmatrix} 1 & 1 \\ 0 & 4 \end{pmatrix}$$

$${}^t P A P = \begin{pmatrix} 1 & 1 \\ 0 & 4 \end{pmatrix} \quad P: \text{直交}$$

$$\Leftrightarrow {}^t P P = P {}^t P = I_3$$

↑  
P ≠ 0.



$$A = \begin{pmatrix} 3 & -1 & -2 \\ -1 & 3 & 2 \\ -2 & 2 & 6 \end{pmatrix} \quad \text{直交} \rightarrow \text{正交}.$$

$$\Phi_A(\lambda) = (\lambda - 2)^2(\lambda - 8)$$