



x	y	z
x_1	y_1	z_1
\vdots	\vdots	\vdots
x_n	y_n	z_n

$$\vec{x} = \frac{1}{\sqrt{2}} \begin{pmatrix} x_1 - \bar{x} \\ \vdots \\ x_n - \bar{x} \end{pmatrix} \quad V(x) = \|\vec{x}\|^2$$

$\vec{y}, \vec{z}: \square \square \square$

$$\vec{w} = \alpha x + \beta y + \gamma z$$

$\alpha, \beta, \gamma: \text{실수}$

$$\vec{w} = \frac{1}{\sqrt{2}} \begin{pmatrix} w_1 - \bar{w} \\ \vdots \\ w_n - \bar{w} \end{pmatrix} = \alpha \vec{x} + \beta \vec{y} + \gamma \vec{z}$$

$$w_i = \alpha x_i + \beta y_i + \gamma z_i$$

$$\bar{w} = \alpha \bar{x} + \beta \bar{y} + \gamma \bar{z}$$

$$w_i - \bar{w} = \alpha (x_i - \bar{x}) + \beta (y_i - \bar{y}) + \gamma (z_i - \bar{z})$$

$$\vec{w} = \alpha \vec{x} + \beta \vec{y} + \gamma \vec{z}$$

$$= (\vec{x} \ \vec{y} \ \vec{z}) \vec{a}$$

$$\vec{a} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

$$V(w) = \|\vec{w}\|^2 = D \vec{a}$$

$$= (D \vec{a}, D \vec{a})$$

$$= (\tau D D \vec{a}, \vec{a})$$

$$\tau D D = \begin{pmatrix} \tau \vec{x} \\ \tau \vec{y} \\ \tau \vec{z} \end{pmatrix} \begin{pmatrix} \vec{x} \ \vec{y} \ \vec{z} \end{pmatrix}$$

$$= \begin{pmatrix} V(x) & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & V(y) & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & V(z) \end{pmatrix}$$

$$(\vec{e}, \vec{e}) = \|\vec{e}\|^2$$

$\square \square \square$

$$\tau \vec{x} \vec{x}$$

$$= \|\vec{x}\|^2$$

$$= V(x)$$

$$\tau \vec{y} \vec{x} = (\vec{y}, \vec{x})$$

$$= \sigma_{xy}$$

$$\square \square \square$$

$$t(tDD) = tD \cdot t(tD) = tDD$$

$$t(AB) = tB^t A$$

$\leadsto tDD$: 対称.

tDD : 0 0 のみを含む.

$$A = (a_{ij}) \quad a_{ij} = a_{ji} \quad \text{対称.}$$

$$tA = A$$

$$(A\vec{v}, \vec{v}) \quad A \text{ の 2 次形式.}$$

$$\underline{n=2} \quad A = \begin{pmatrix} a & c \\ c & b \end{pmatrix} \quad \text{対称.}$$

$$\bar{\Phi}_A(\lambda)$$

$$= \det(\lambda I_2 - A) = \begin{vmatrix} \lambda - a & -c \\ -c & \lambda - b \end{vmatrix}$$

$$= (\lambda - a)(\lambda - b) - c^2$$

$$= \lambda^2 - (a+b)\lambda + (ab - c^2)$$

$$D = (a+b)^2 - 4(ab - c^2)$$

$$= (a-b)^2 + 4c^2 \geq 0$$

• $\bar{\Phi}_A(\lambda)$ が 2 重根 ならば.

• $\bar{\Phi}_A(\lambda)$ が 2 重根 ならば $\Leftrightarrow D = 0$

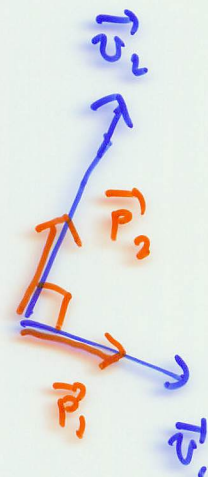
$$\Leftrightarrow a = b, c = 0$$

$$A = \begin{pmatrix} a & 0 \\ 0 & a \end{pmatrix} = aI_2$$

$$\vec{p}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1, \quad \vec{p}_2 = \frac{1}{\|\vec{v}_2\|} \vec{v}_2$$

$$\|\vec{p}_1\| = \|\vec{p}_2\| = 1, \quad (\vec{p}_1, \vec{p}_2) = 0$$

$$P = (\vec{p}_1, \vec{p}_2) : \text{orthonormal basis.}$$



$$\begin{aligned} {}^t P P &= \begin{pmatrix} \boxed{{}^t \vec{p}_1} \\ \boxed{{}^t \vec{p}_2} \end{pmatrix} (\vec{p}_1, \vec{p}_2) \\ &= \begin{pmatrix} \|\vec{p}_1\|^2 & (\vec{p}_1, \vec{p}_2) \\ (\vec{p}_1, \vec{p}_2) & \|\vec{p}_2\|^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{aligned}$$

$$\leadsto {}^t P P = I_2$$

$$\det({}^t P P) = \det(I_2) = 1$$

"

$$\det({}^t P) \det(P) = \det(P)^2$$

$$\boxed{\det({}^t C) = \det(C)}$$

$$\leadsto \det(P) = \pm 1 \neq 0$$

$$P: \text{orthonormal basis.}$$

$$\begin{aligned} {}^t P P &= I_2 \\ \cdot P^{-1} &\rightarrow {}^t P = P^{-1} \end{aligned}$$

$$P {}^t P = I_2$$

$$\underline{\text{orthonormal basis}}$$

$${}^t P P = P {}^t P = I_2$$

$$D > 0 \text{ 且 } \lambda \neq \mu \implies \Phi_A(\lambda) = (\lambda - \alpha)(\lambda - \beta)$$

$$(A = \alpha I_2 \text{ 且 } \lambda \neq \mu) \quad \alpha \neq \beta$$

$$\begin{array}{lll} \alpha \text{ 的特征向量} & \vec{u}_1 \neq \vec{0} & A\vec{u}_1 = \alpha\vec{u}_1 \\ \beta & \vec{u}_2 \neq \vec{0} & A\vec{u}_2 = \beta\vec{u}_2 \\ \hline & \vec{u}_1 \neq \vec{u}_2 & \end{array}$$

线性无关

A 的特征值

$\alpha_i \neq \alpha_j$ 的特征值

$$A\vec{u}_i = \alpha_i \vec{u}_i \quad (i=1, \dots, k)$$

$$\begin{cases} c_1 \vec{u}_1 + \dots + c_k \vec{u}_k = \vec{0} \\ \implies c_1 = c_2 = \dots = c_k = 0 \end{cases}$$

$\vec{u}_1, \dots, \vec{u}_k$ 线性无关

证明

$$(\vec{u}_1, \vec{u}_2) = 0$$

$$\begin{aligned} (A\vec{u}_1, \vec{u}_2) &= (\vec{u}_1, {}^t A \vec{u}_2) = (\vec{u}_1, A\vec{u}_2) \\ &= (\alpha \vec{u}_1, \vec{u}_2) = (\vec{u}_1, \beta \vec{u}_2) \\ &= \alpha (\vec{u}_1, \vec{u}_2) = \beta (\vec{u}_1, \vec{u}_2) \end{aligned}$$

$$\implies (\alpha - \beta) (\vec{u}_1, \vec{u}_2) = 0$$

$\neq 0$

$$\implies (\vec{u}_1, \vec{u}_2) = 0$$

$$A \vec{p}_1 = \alpha \vec{p}_1, \quad A \vec{p}_2 = \beta \vec{p}_2$$

$$A (\vec{p}_1 \vec{p}_2) = (\vec{p}_1 \vec{p}_2) \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}$$

$${}^t P A P = \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} \quad P^{-1} = {}^t P.$$

$$A = P \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} {}^t P$$

${}^t P \in \mathbb{O}_2$.

$${}^t P \cdot {}^t ({}^t P) = {}^t P P = I_2$$

$${}^t ({}^t P) {}^t P = P {}^t P = I.$$

$$\rightarrow {}^t ({}^t P) {}^t P = {}^t P {}^t ({}^t P) = I_2$$

$$(A \vec{u}, \vec{u}) = \left(\cancel{{}^t P A P} \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} \vec{u}, \vec{u} \right)$$

$$\rightarrow (P \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} {}^t P \vec{u}, \vec{u})$$

$$= \left(\begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} {}^t P \vec{u}, {}^t P \vec{u} \right)$$

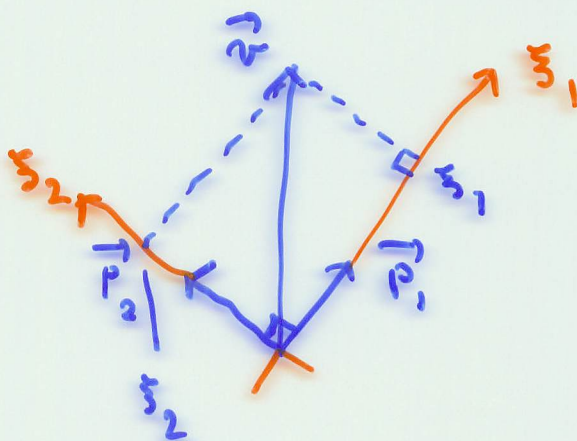
$${}^t P \vec{u} = \vec{\xi} = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \quad \vec{u} = P \vec{\xi}$$

$$= \left(\begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix}, \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \right)$$

$$= \left(\begin{pmatrix} \alpha \xi_1 \\ \beta \xi_2 \end{pmatrix}, \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \right)$$

$$= \alpha \xi_1^2 + \beta \xi_2^2$$

$$\vec{v} = P \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = (\vec{p}_1 \vec{p}_2) \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \\ = \xi_1 \vec{p}_1 + \xi_2 \vec{p}_2$$



$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \quad \Phi_A(\lambda) = (\lambda - 1)^2 (\lambda - 4)$$

$$\underline{V(1)} \quad I_3 - A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

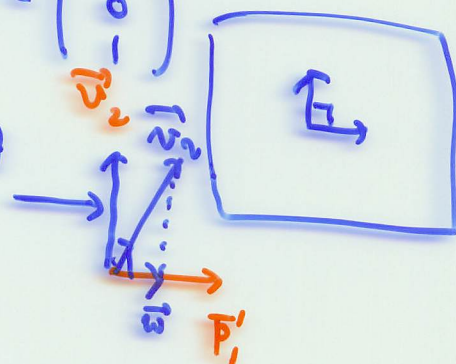
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -y - z \\ y \\ z \end{pmatrix} = y \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad x + y + z = 0$$

$$\vec{p}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$$

$$\vec{p}_2 = \frac{1}{\|\vec{v}_2\|} \vec{v}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\vec{p}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\vec{p}_3 = \frac{1}{\|\vec{v}_3\|} \vec{v}_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$



$$\underline{V(4)} \quad 4I_3 - A = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{pmatrix} - \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & -1 & 2 \\ -1 & 2 & -1 \\ 2 & -1 & -1 \end{pmatrix}$$

inter

$$\begin{pmatrix} 1 & 1 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \leftarrow \leftarrow \begin{pmatrix} 1 & 1 & -2 \\ 0 & 3 & -3 \\ 0 & -3 & 3 \end{pmatrix} \leftarrow \begin{pmatrix} 1 & 1 & -2 \\ -1 & 2 & -1 \\ 2 & -1 & -1 \end{pmatrix}$$

$$\downarrow$$

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix}$$

$$x = 2$$

$$y = 2$$

$$\begin{array}{r} 2 \quad -1 \quad -1 \\ - \quad 2 \quad 2 \quad -4 \end{array}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \vec{p}_3 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\|\vec{p}_1\| = \|\vec{p}_2\| = \|\vec{p}_3\| = 1$$

$$(\vec{p}_1, \vec{p}_2) = 0$$

$$(\vec{p}_1, \vec{p}_3) = (\vec{p}_2, \vec{p}_3) = 0$$

定理

A : 3x3 matrix. α, β 实数
 $\alpha \neq \beta$

$$A \vec{u}_1 = \alpha \vec{u}_1$$

$$A \vec{u}_2 = \beta \vec{u}_2$$

$$\rightarrow (\vec{u}_1, \vec{u}_2) = 0$$

$$P = (\vec{p}_1 \vec{p}_2 \vec{p}_3)$$

$$P^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\rightarrow P^{-1}P = I$$

$$P^{-1}P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$AP = P \begin{pmatrix} 1 & & \\ & 1 & \\ & & 4 \end{pmatrix}$$

$${}^t P A P = \begin{pmatrix} 1 & & \\ & 1 & \\ & & 4 \end{pmatrix} \quad P: \text{ invertible}$$

$$\Leftrightarrow {}^t P P = P {}^t P = I_3$$

↑
orthogonal



$$A = \begin{pmatrix} 3 & -1 & -2 \\ -1 & 3 & 2 \\ -2 & 2 & 6 \end{pmatrix} \quad \text{symmetric matrix.}$$

$$\bar{\Phi}_A(\lambda) = (\lambda - 2)^2 (\lambda - 8)$$