

I

$$A = \begin{pmatrix} 2 & 0 & 2 \\ 1 & -1 & -2 \\ -1 & 3 & 5 \end{pmatrix}$$

$$A \vec{v} = \lambda I_3 \vec{v}$$

$$(\lambda I_3 - A) \vec{v} = \vec{0}$$

$$\boxed{A \vec{v} = \lambda \vec{v}}, \vec{v} \neq \vec{0} \quad \text{means } \vec{v} \text{ is an eigenvector}$$

$$\Leftrightarrow |\lambda I_3 - A| = 0$$

↖ 有 9 个方程

B:  $n \times n$  的实数矩阵.

$$(B \vec{x} = \vec{0} \Rightarrow \vec{x} = \vec{0}) \Leftrightarrow \det(B) \neq 0$$

$$\Leftrightarrow B: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$\left( B \vec{x} = \vec{0}, \vec{x} \neq \vec{0} \text{ 存在} \right) \Leftrightarrow \det(B) = 0$$

$$|\lambda I_3 - A| = (\lambda - 1)(\lambda - 2)(\lambda - 3)$$

$$\underline{\lambda = 1} \quad \vec{p}_1 = \begin{pmatrix} -2 \\ -2 \\ 1 \end{pmatrix}$$

$$\underline{\lambda = 2} \quad \vec{p}_2 = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} \quad \underline{\lambda = 3} \quad \vec{p}_3 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

$$P = (\vec{p}_1 \vec{p}_2 \vec{p}_3)$$

$$AP = (A \vec{p}_1 \ A \vec{p}_2 \ A \vec{p}_3) = (\vec{p}_1 \ \vec{p}_2 \ 3 \vec{p}_3)$$

$$= (\vec{p}_1 \ \vec{p}_2 \ \vec{p}_3) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix} = P \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

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例 4)

$$(\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_\ell) \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_\ell \end{pmatrix} = c_1 \vec{a}_1 + c_2 \vec{a}_2 + \dots + c_\ell \vec{a}_\ell$$

$$|P| = \begin{vmatrix} -2 & 3 & 2 \\ -2 & 1 & 0 \\ \textcircled{1} & 0 & 1 \end{vmatrix} = \begin{vmatrix} 0 & 3 & 4 \\ 0 & 1 & 2 \\ 1 & 0 & 1 \end{vmatrix} = \begin{vmatrix} 3 & 4 \\ 1 & 2 \end{vmatrix} = 6 - 4 = 2 \neq 0$$

$\leadsto P: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

定理  $A: n \times n$  正交阵

$\alpha_1, \dots, \alpha_k: \mathbb{R}$  有通.

$$\alpha_i \neq \alpha_j \quad (i \neq j)$$

$$A \vec{v}_i = \alpha_i \vec{v}_i \quad (i=1, \dots, k)$$

$$\vec{v}_1 + \dots + \vec{v}_k = \vec{0} \Rightarrow \vec{v}_1 = \dots = \vec{v}_k = \vec{0}$$

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$k$  个非零向量  $\vec{v}_1, \dots, \vec{v}_k$   $k=1$  时显然.

$$\textcircled{1} \times \alpha_k \quad \alpha_k \vec{v}_1 + \alpha_k \vec{v}_2 + \dots + \alpha_k \vec{v}_{k-1} + \cancel{\alpha_k \vec{v}_k} = \vec{0}$$

$$A \cdot \textcircled{1} \quad \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_{k-1} \vec{v}_{k-1} + \cancel{\alpha_k \vec{v}_k} = \vec{0}$$

$$(\alpha_k - \alpha_1) \vec{v}_1 + (\alpha_k - \alpha_2) \vec{v}_2 + \dots + (\alpha_k - \alpha_{k-1}) \vec{v}_{k-1} = \vec{0}$$

$$A(\vec{v}_1 + \dots + \vec{v}_k) = A\vec{v}_1 + A\vec{v}_2 + \dots + A\vec{v}_k$$

$$= \alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_k \vec{v}_k$$

$$A(\alpha_k - \alpha_1) \vec{v}_1 = (\alpha_k - \alpha_1) (A\vec{v}_1)$$

$$= (\alpha_k - \alpha_1) \alpha_1 \vec{v}_1$$

$$= \alpha_1 (\alpha_k - \alpha_1) \vec{v}_1$$

$\vec{v}_1 \neq \vec{0}$

非零向量  $\vec{v}_1$

$$(\alpha_k - \alpha_1) \vec{v}_1 = \dots = (\alpha_k - \alpha_{k-1}) \vec{v}_{k-1} = \vec{0}$$

$\neq 0$        $\neq 0$

$$\leadsto \vec{v}_1 = \vec{v}_2 = \dots = \vec{v}_{k-1} = \vec{0} \leadsto \vec{v}_k = \vec{0}$$



$$\vec{p}_1, \vec{p}_2, \vec{p}_3$$

$$A\vec{p}_1 = \vec{p}_1, \quad A\vec{p}_2 = 2\vec{p}_2, \quad A\vec{p}_3 = 3\vec{p}_3$$

$$(\vec{p}_1, \vec{p}_2, \vec{p}_3) \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \underbrace{c_1 \vec{p}_1}_{=\vec{v}_1} + \underbrace{c_2 \vec{p}_2}_{=\vec{v}_2} + \underbrace{c_3 \vec{p}_3}_{=3\vec{v}_3} = \vec{0}$$

$$\alpha_1 = 1, \quad \alpha_2 = 2, \quad \alpha_3 = 3$$

$$\begin{aligned} A\vec{v}_3 &= A c_3 \vec{p}_3 \\ &= c_3 A \vec{p}_3 \\ &= 3 c_3 \vec{p}_3 = 3 \vec{v}_3 \end{aligned}$$

$$\rightarrow c_1 \vec{p}_1 = c_2 \vec{p}_2 = c_3 \vec{p}_3 = \vec{0} \leadsto c_1 = c_2 = c_3 = 0$$

$$\vec{p}_1 \neq \vec{0}, \quad \vec{p}_2 \neq \vec{0}, \quad \vec{p}_3 \neq \vec{0}$$

$$\bullet \left( P \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \vec{0} \Rightarrow \vec{c} = \vec{0} \right)$$

$$\Leftrightarrow \det(P) \neq 0 \Leftrightarrow P: \mathbb{R}^3 \rightarrow \mathbb{R}^3.$$

$$\Phi_A(\lambda) = \lambda^n - (a_{11} + a_{22} + \dots + a_{nn})\lambda^{n-1} + \dots + (-1)^n \det(A) = 0.$$

$$\text{tr}(A) = a_{11} + a_{22} + \dots + a_{nn}$$

$$A = (a_{ij}) \quad A \text{ の trace, 跡.}$$

代数学の基本定理.

$$f(\lambda) = \lambda^n + a_{n-1}\lambda^{n-1} + \dots + a_1\lambda + a_0$$

$$\leadsto f(\lambda) = (\lambda - \alpha_1) \dots (\lambda - \alpha_n)$$

$$\alpha_1, \dots, \alpha_n \in \mathbb{C}$$

$$\lambda^2 + 1 = (\lambda - i)(\lambda + i)$$

$A: n \times n$  正則行列.

$$\Phi_A(\lambda) = (\lambda - \alpha_1) \dots (\lambda - \alpha_n)$$

$$\alpha_1, \alpha_2, \dots, \alpha_n \in \mathbb{C}$$

$\mathbb{C}$  上で.

定理  $A: n \times n$  正則行列

$$\alpha_1, \dots, \alpha_n: \mathbb{C} \text{ 上で.}$$

$$\alpha_i \neq \alpha_j \quad (i \neq j)$$

$$A \vec{p}_i = \alpha_i \vec{p}_i \quad (\vec{p}_i \neq \vec{0})$$

$\Rightarrow$

$$AP = P \begin{pmatrix} \alpha_1 & & \\ & \ddots & \\ & & \alpha_n \end{pmatrix}, \quad P = (\vec{p}_1 \dots \vec{p}_n)$$

正則.

$\Phi_A(\lambda)$  の根

$\Rightarrow A$  は対角化可能.



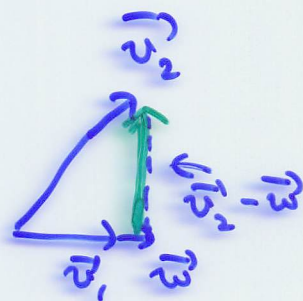
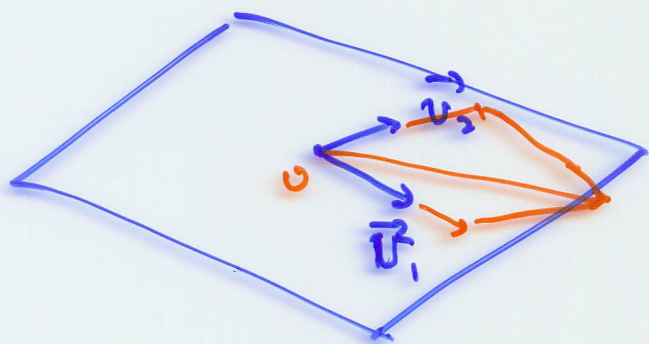
$$V(z) = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix}; A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 2 \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right\}$$

$$= \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix}; x - y - 2z = 0 \right\}$$

$$\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \vec{v}_2 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

$$= \mathbb{R} \vec{v}_1 + \mathbb{R} \vec{v}_2$$

$$= \{ c_1 \vec{v}_1 + c_2 \vec{v}_2; c_1, c_2 \in \mathbb{R} \}$$



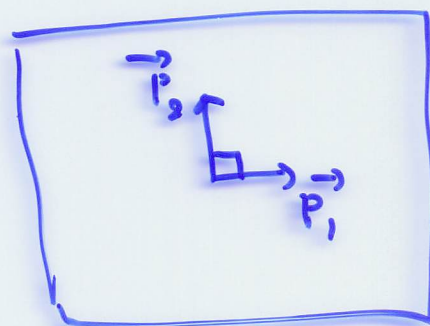
$$\vec{v}_1 \leadsto \vec{p}_1 = \frac{1}{\|\vec{v}_1\|} \vec{v}_1 = \frac{1}{\sqrt{2}} \vec{v}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\vec{u}_1 = \frac{(\vec{v}_1, \vec{v}_2)}{\|\vec{v}_1\|^2} \cdot \vec{v}_1 = \frac{2}{2} \vec{v}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\vec{v}_2 - \vec{u}_1 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$$\vec{p}_2 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$$

$V(z)$



$$\begin{cases} A \vec{p}_1 = 2 \vec{p}_1 \\ A \vec{p}_2 = 2 \vec{p}_2 \end{cases}$$

$$\|\vec{p}_1\| = \|\vec{p}_2\| = 1$$

$$(\vec{p}_1, \vec{p}_2) = 0$$

部分空間を基底とする。

$P: \mathbb{C} \ni z \mapsto \bar{z}$ .

$$\lambda^2 + 1 = (\lambda - i)(\lambda + i)$$

③  $A: \text{実}, \alpha_1, \dots, \alpha_n \in \mathbb{R} \Rightarrow P: \text{実}$ .

$$A = \begin{pmatrix} 3 & -1 & -2 \\ -1 & 3 & 2 \\ -2 & 2 & 6 \end{pmatrix}$$

$${}^t A = A$$

$A: \text{対称}.$

$$A = \begin{pmatrix} \alpha & \beta \\ \beta & \gamma \end{pmatrix} \quad P: \text{回転} \\ = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$${}^t A = A$$

$$AP = P \begin{pmatrix} \alpha & 0 \\ 0 & \beta \end{pmatrix}$$

$$(A \begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} x \\ y \end{pmatrix}) = \alpha x^2 + 2\beta xy + \gamma y^2$$

$$= \alpha \xi^2 + \beta \eta^2$$

$$|\lambda I_3 - A| = (\lambda - 2)^2 \times (\lambda - 8)$$

$$\lambda = 2$$

$$2I_2 - A = \begin{pmatrix} -1 & 1 & 2 \\ 1 & -1 & -2 \\ 2 & -2 & -4 \end{pmatrix} \rightarrow \dots \rightarrow \begin{pmatrix} 1 & -1 & -2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}: (2I_2 - A) \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \vec{0} \Leftrightarrow x - y + 2z = 0$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} y - 2z \\ y \\ z \end{pmatrix} = y \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + z \begin{pmatrix} -2 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda = 8$$

$$8I_3 - A \rightarrow \dots \rightarrow \begin{pmatrix} 1 & 0 & \frac{1}{2} \\ 0 & 1 & -\frac{1}{2} \\ 0 & 0 & 0 \end{pmatrix} = \begin{pmatrix} -\frac{1}{2}z \\ \frac{1}{2}z \\ z \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}: \begin{cases} x + \frac{1}{2}z = 0 \\ y - \frac{1}{2}z = 0 \end{cases}$$

$$= \frac{1}{2}z \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$



$$V(2) = \{ \vec{v}; A\vec{v} = 2\vec{v} \}$$

$$= \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix}; \boxed{x - y - 2z = 0} \right\}$$

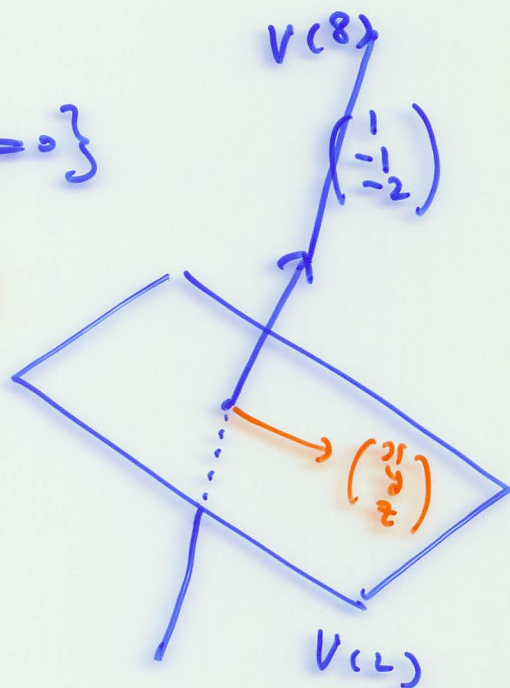
$$V(8) = \mathbb{R} \vec{v}_3$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$$

$$\vec{p}_3 = \frac{1}{\|\vec{v}_3\|} \vec{v}_3$$

$$\vec{v}_3 = \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$

$$= \frac{1}{\sqrt{6}} \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$$



$$\|\vec{p}_i\| = 1 \quad (i=1, 2, 3)$$

$$(\vec{p}_i, \vec{p}_j) = 0 \quad (i \neq j)$$

$$P = (\vec{p}_1, \vec{p}_2, \vec{p}_3)$$

通过验证.

平行

$$AP = P \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{pmatrix}$$

$$\left( A \begin{pmatrix} x \\ y \\ z \end{pmatrix}, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right) = 2x^2 + 2y^2 + 8z^2$$

$$A = \begin{pmatrix} 1 & 2 & 2 & 0 & -3 \\ 2 & 4 & 4 & 3 & 0 \\ -1 & -1 & 1 & 0 & 3 \\ 0 & 1 & 3 & 2 & 4 \end{pmatrix}$$

$$A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \vec{0} \quad \text{ist.}$$