

Renormalization group approach to an extension of the law of iterated logarithms for one-dimensional (non-Markovian) stochastic chain

RIMS, 2003.9.10

Kumiko HATTORI (Shinshu U.)

Tetsuya HATTORI (Nagoya U.)

Tetsuya Hattori, *Random walks and renormalization groups — an introduction to mathematical physics*, Kyoritsu publishing, 2004.3, to appear (in Japanese).

1. Introduction
 - Expectation on ‘Mathematics’ of RG
2. Law of iterated logarithms (LIL)
 - Asymptotic behavior (‘exponent’) of paths
3. Main results
 - RG, construction of stochastic chains, generalized LIL
4. Displacement exponent for self-repelling walk

§1. Introduction.

- ‘Mathematics’ of RG (still a long way to go)
— a mathematical tool (calculus), and structure
- Return to a simplest model
scale change of the accuracy of observation
— Stochastic chains (probability measure on the set of paths) on \mathbb{Z} , with 1-dimensional RG (nearest neighbor jumps)
- ‘A diet coke is good after chinese dishes.’ (K.R.Ito)

We also have corresponding results on the following:

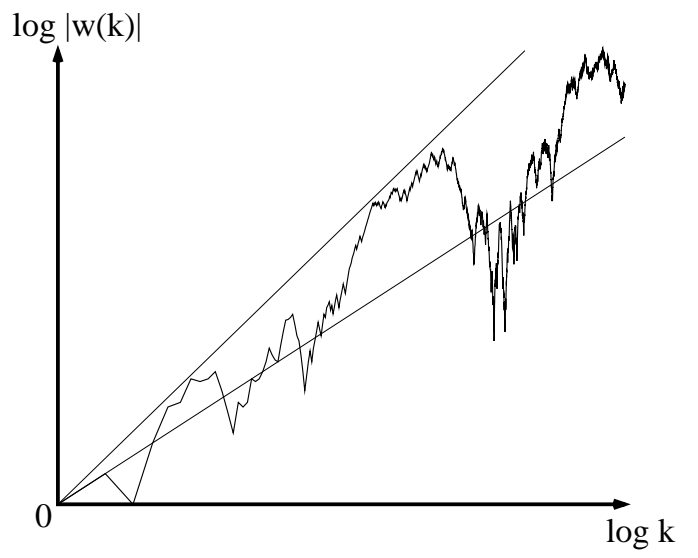
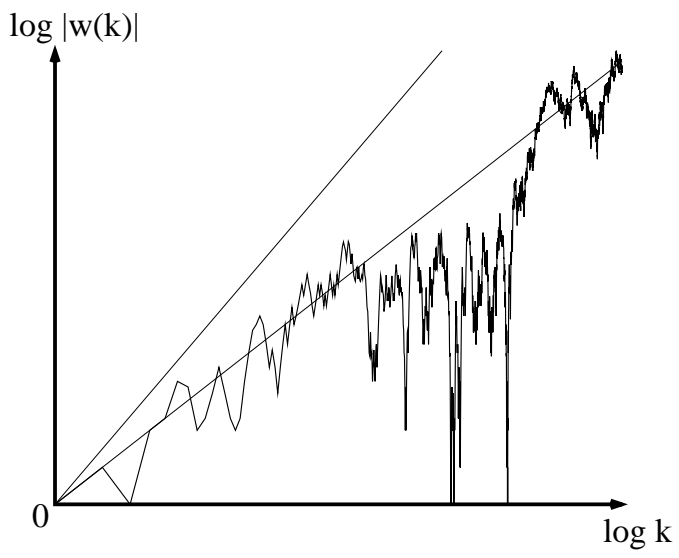
- Continuum limit continuous processes
- Chains and processes on the Sierpinski gasket
Hambly, K.Hattori, T.Hattori, PTRF 124 (2002)
K.Hattori, T.Hattori, preprint, 2003

§2. Law of iterated logarithms (LIL).

Theorem (Khintchine, 1924). Let $W_k, k \in \mathbb{Z}_+$, be SRW on \mathbb{Z} with $W_0 = 0$. Then

$$\mathbb{P}\left[\overline{\lim}_{k \rightarrow \infty} \frac{W_k}{\sqrt{k \log \log k}} = 1 \right] = 1. \quad \diamond$$

- $W_k \sim k^{1/2}$ (as for CLT and displacement exponent). log log correction is automatic from RG — The exponent 1/2 is a consequence of fluctuations, hence path fluctuates around the average $k^{1/2}$



What is new in our work?

- Previous works — exponent $\nu = 1/2$

We generalize to all ν — existence proof of a chain with exponent ν .

- Decimation for SRW known. (F.B.Knight, 1962)

We do not use Markov properties. (Note $\nu \neq 1/2$ suggests non-Markov.)

RG as a new math. to analyze non-Markov proc.

Remark.

Why LIL and not displacement exponent?

$$E[w(k)^s] \sim k^{\nu s}$$

For Markov chains displacement exponents are easier because of independence of increments $W_{k+1} - W_k$, but we are working on non-Markovian chains!

- Displacement exponent for self-repelling walks (K.Hattori, T.Hattori, 2003)

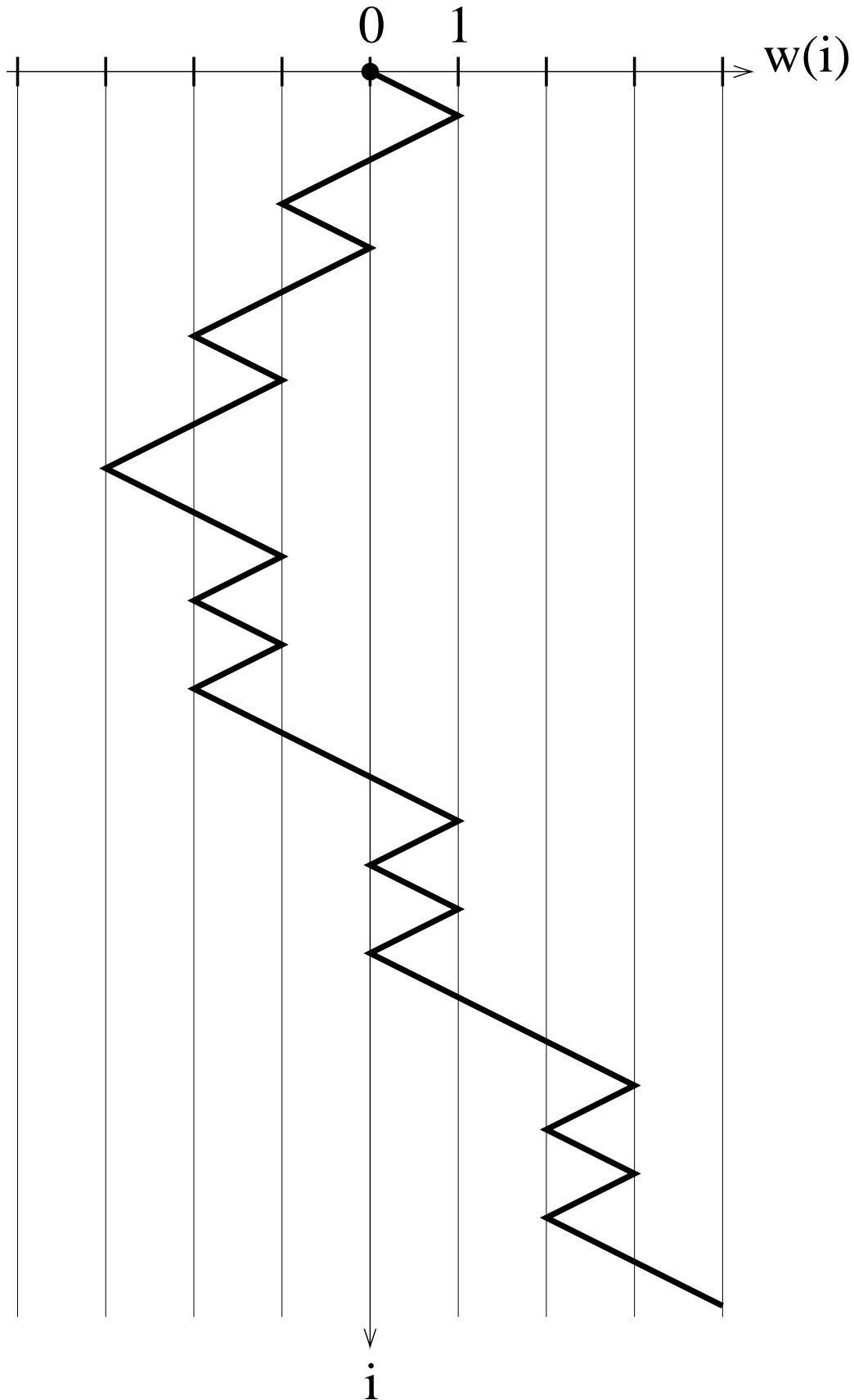
§3. Main results.

Path on \mathbb{Z} .

$L \in \mathbb{Z}$ or $L = \infty$ (length).

$w : \{0, 1, \dots, L\} \rightarrow \mathbb{Z}$;

$w(0) = 0, |w(i) - w(i-1)| = 1, i = 1, \dots, L$

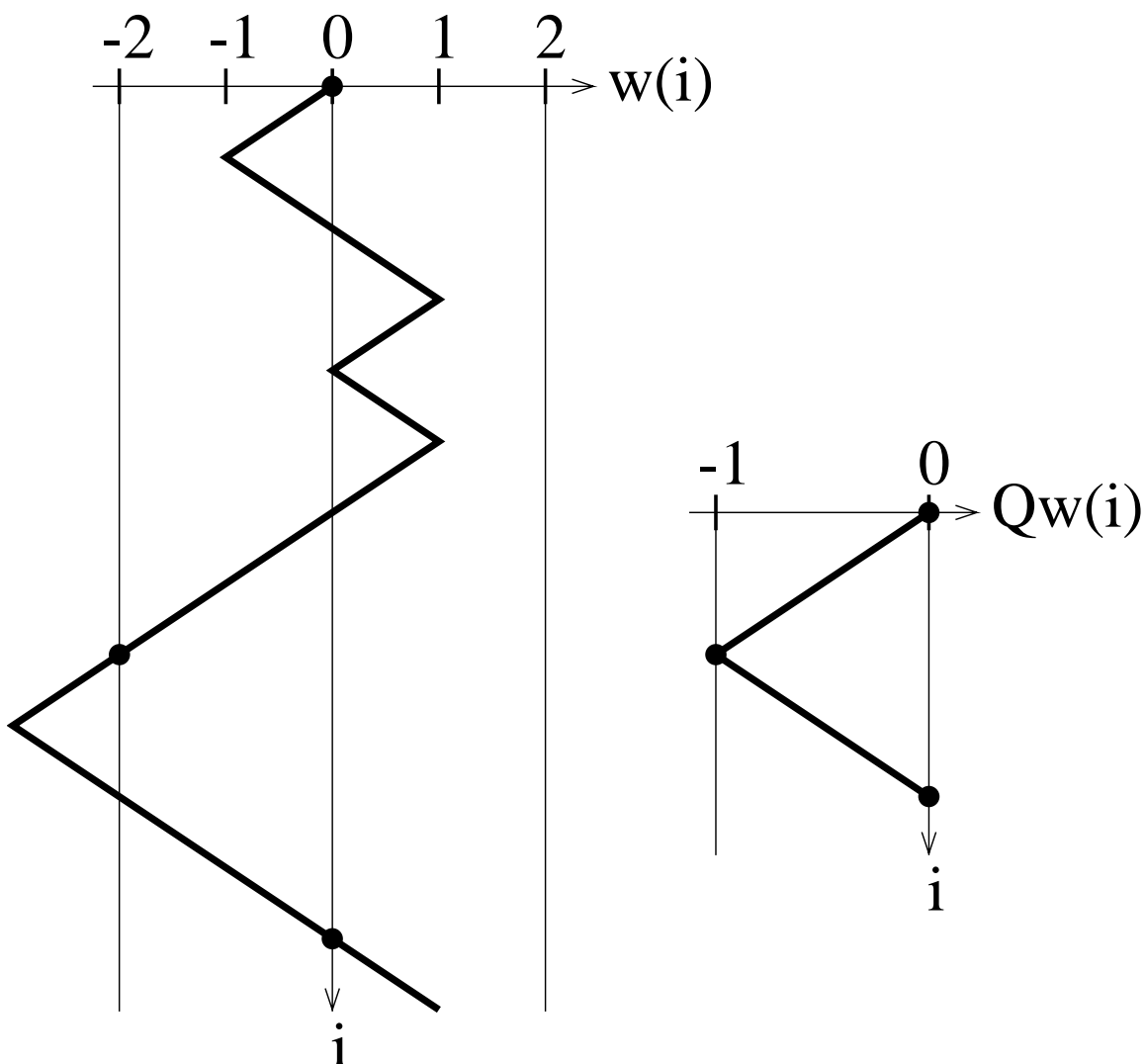


Stochastic chain = Prob. measure on the set of $L = \infty$ paths

1. Decimation
2. Analysis of RG
3. Construction of chains consistent with RG
4. Asymptotics from RG (generalized LIL)

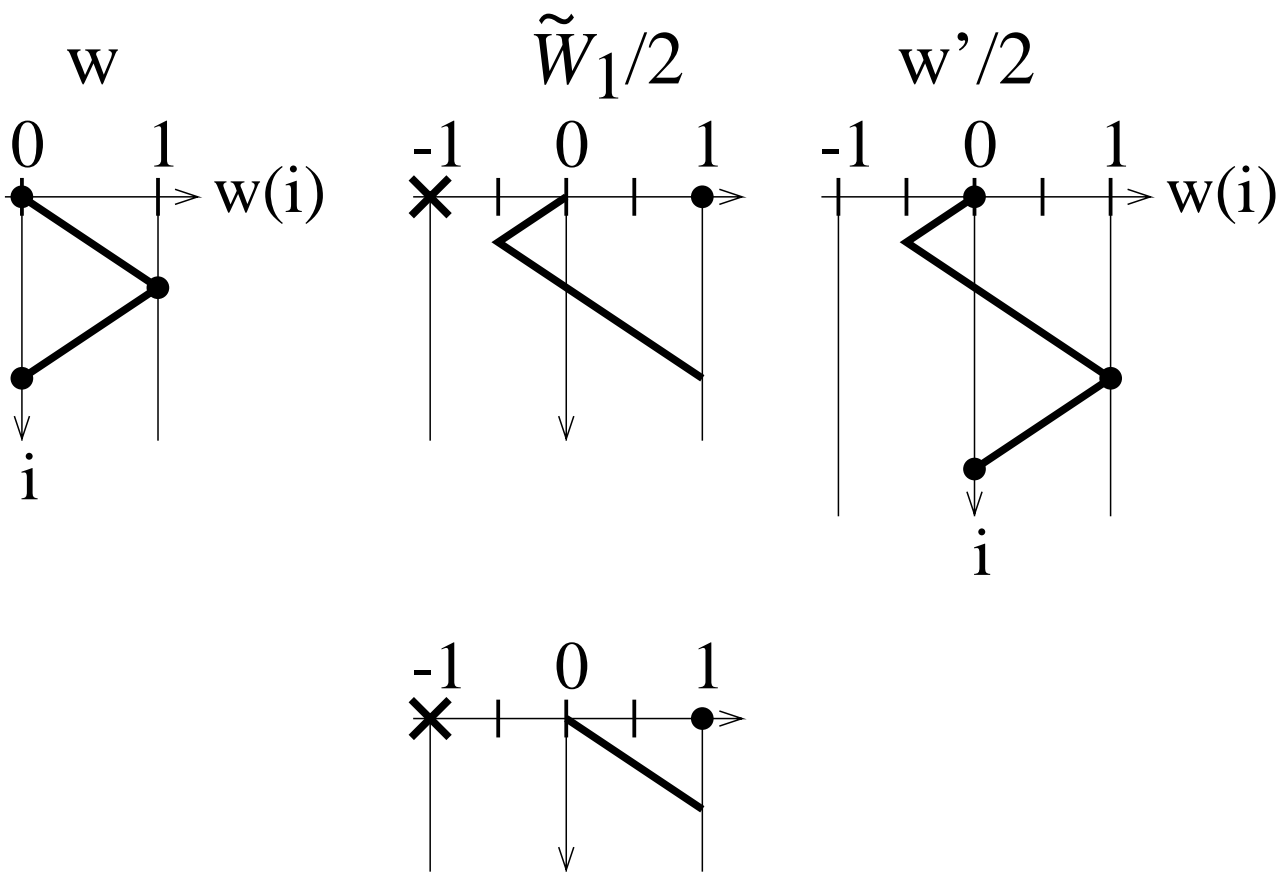
1. Decimation. Scale change of the accuracy of observation

$$Q : w \mapsto Qw; (Qw)(i) = \frac{1}{2}w(T_i(w)); T_0(w) = 0, \\ T_{i+1}(w) = \inf\{j > T_i(w) \mid w(j) \in 2\mathbb{Z} \setminus \{w(T_i(w))\}\}$$



'Fine structures' lost by Q (added by Q^{-1}):

\tilde{W}_1 : set of paths; $L < \infty$, ending at 2, which do not hit -2 .



$$\Phi_1(z) = \sum_{w \in \tilde{W}_1} b_1(w) z^{L(w)} =: \sum_{k=0}^{\infty} c_k z^k.$$

(Note $c_0 = c_1 = 0$.)

Assumptions on b_1 (or c_k):

- (i) $b_1(w) \geq 0$
- (ii) radius of convergence $r > 0$
- (iii) $c_2 > 0$ and $\exists k \geq 3; c_k > 0$

Proposition.

- (i) $\exists! x_c; \Phi_1(x_c) = x_c, 0 < x_c < r$
- (ii) $\lambda := \Phi_1'(x_c) > 2$

◇

(SRW: $\Phi_1(z) = \frac{x^2}{1-2x^2}, x_c = 1/2, \lambda = 4$)

RG: the dynamical system determined by Φ_1

$$\Phi_{n+1} = \Phi_1 \circ \Phi_n, n = 1, 2, 3, \dots$$

Note $\Phi_n(z) = \sum_{w \in \tilde{W}_n} b_n(w) z^{L(w)}; \tilde{W}_n: 0 \rightarrow 2^n, \rightarrow 2^n$

— Representation in the parameter space of the scale change (addition of fine structure \tilde{W}_1)

2. Analysis of RG.

$\underline{P}_n[\{w\}] := b_n(w)x_c^{L(w)-1}$ defines prob. meas. on \tilde{W}_n

\tilde{P}_n : scaled length distribution on \tilde{W}_n ;

$$\int e^{-s\xi} \tilde{P}_n[d\xi] = x_c^{-1} \Phi_n(e^{-\lambda^{-n}s} x_c)$$

$$(= \sum_{w \in \tilde{W}_n} e^{-s\lambda^{-n}L(w)} \underline{P}_n[\{w\}])$$

Theorem. $\exists \tilde{P}_*$; $\tilde{P}_n \rightarrow \tilde{P}_*$. Additional estimates on rate of convergence and limiting distributions such as:

(i) $\exists \rho(\xi) d\xi = \tilde{P}_*[d\xi]$, C^∞ , positive.

(ii) $\nu = \log 2 / \log \lambda$,

$$-C \leq \underline{\lim}_{x \rightarrow 0} x^{\nu/(1-\nu)} \log \tilde{P}_*[[0, x]] \leq \overline{\lim} \leq -C',$$

$x > 0$

◇

Note $\exists \rho(\xi)$ implies non-deterministic (non-trivial).

$$k \sim \lambda^n \Leftrightarrow x = 2^n \Rightarrow x \sim k^\nu$$

3. Chains consistent with RG.

(\tilde{W}_n, P_n) : paths with fixed endpoints. \leftrightarrow

Chain: meas. on infinite length path (LIL considers limit for each path) with pos. at fixed length W_k measurable

\tilde{W}_n^r : \tilde{W}_n with $w \mapsto -w$

Prob. meas. $P_{r,n}$ on \tilde{W}_n^r ; $P_{r,n}[\{w\}] = P_n[\{-w\}]$

Theorem (Hattori—Hattori, 2003).

$\exists\{W_k\}; (\forall w; L(w) = k)(\forall n; 2^n > \max_{0 \leq j < k} |w(j)|)$

$P[W_j = w(j), 0 \leq j \leq k]$

$= \frac{1}{2}P_n[\{w' \in \tilde{W}_n \mid w'(j) = w(j), 0 \leq j \leq k\}]$

$+ \frac{1}{2}P_{r,n}[\{w' \in \tilde{W}_n^r \mid w'(j) = w(j), 0 \leq j \leq k\}]$

◇

RG serves as consistency condition!

4. Asymptotics from RG (generalized LIL).

Theorem (Hattori—Hattori, 2003).

Let $\nu = \frac{\log 2}{\log \lambda}$; $\lambda = \Phi'(x_c)$. Then $\exists C_{\pm} > 0$;

$$\mathbb{P} \left[C_- \leq \overline{\lim}_{k \rightarrow \infty} \frac{|W_k|}{k^{\nu} (\log \log k)^{1-\nu}} \leq C_+ \right] = 1 \quad \diamond$$

Idea of proof.

- RG estimates on hitting time of $2^n \rightarrow \mathbb{P}[W_k < C2^n]$.
- Prob. 1 statement from (modified) Borel-Cantelli Th. for scale parameter n .

Lower bd: BC2 (independence among scales). cf. Previous results on SRW: BC2 for step number $k \leftarrow$ requires Markov property.

$$\{A_k\} \perp, \sum_{k=1}^{\infty} \mathbb{P}[A_k] = \infty \rightarrow \mathbb{P} \left[\overline{\lim}_{k \rightarrow \infty} A_k \right] = 1$$

§4. Displacement exponent for self-repelling walk.

SRW — Markov, $\nu = 1/2$; $|W_k| \sim k^\nu$

Self-avoiding path — non-Markov extreme, $\nu = 1$ on \mathbb{Z}

• continuous interpolation?

Theorem (Hattori—Hattori, 2003). \exists measures on $L = \infty$ path P_u , $u \in [0, 1]$;

1. $u = 1$: SRW on \mathbb{Z} (or Sierpiński gasket)
2. $u = 0$: SAP
3. Displacement exponent

$$\lim_{k \rightarrow \infty} \frac{1}{\log k} \log \mathbb{E}_u[|W_k|^s] = s\nu_u, \quad s \geq 0,$$

is conti. in u

Construction for measures on \mathbb{Z} :

Generating function of L for SAP $\Phi_{0,1}(z) = z^2$

Generating function for SRW

$$\Phi_{1,1}(z) = \Phi_1(z) = \frac{z^2}{1 - 2z^2}$$

Interpolation! $\Phi_{u,1}(z) = \frac{z^2}{1 - 2u^2 z^2}$

$$\nu_u = \frac{\log 2}{\log \lambda_u}, \quad \lambda_u = \Phi'_{u,1}(x_{c,u}), \quad x_{c,u} = \Phi_{u,1}(x_{c,u})$$

displacement exponent \leftarrow reflection principle \leftarrow explicit form of weights

